

# Reduced-order modeling of laminar-turbulent transition in large-eddy simulations

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CENTER FOR TURBULENCE RESEARCH



Advanced Modeling and Simulation Seminar Series  
NASA/Ames May 2019



# Stability research at CTR

Flow separation

High-speed flows

Jet noise

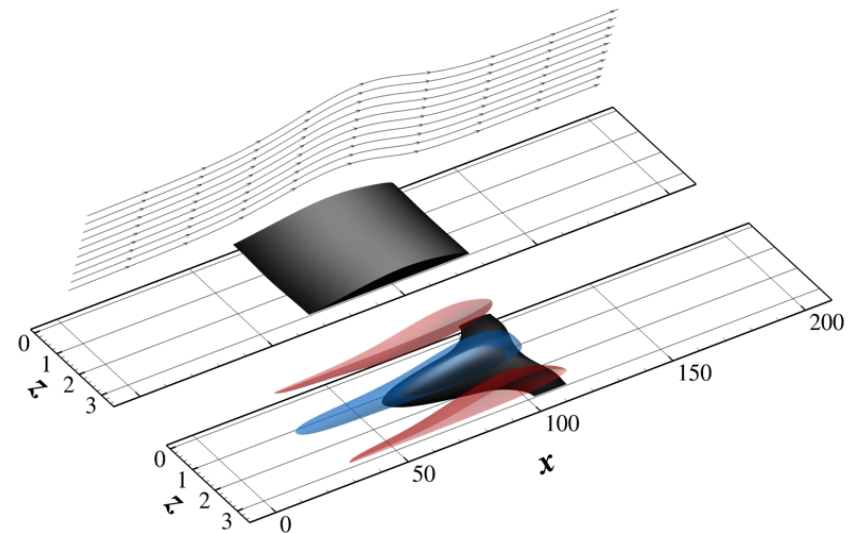
Nonlinear stability

Atomization

Reduced-order modeling

Flow separation reduces aerodynamic performance

- How can separation be delayed/avoided most effectively?
- Most effective mechanism of separation delay exploits the gradients provided by the mean shear



# Stability research at CTR

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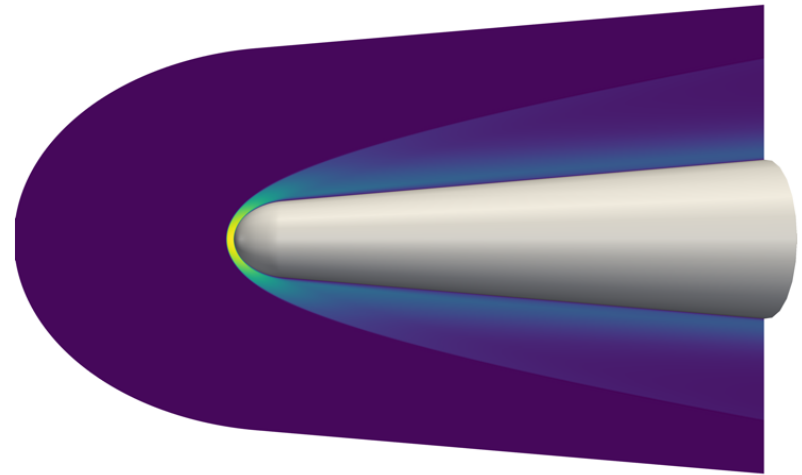
Nonlinear stability

Atomization

Reduced-order modeling

## Transition to turbulence in hypersonic flows

- Breakdown to turbulence critically increases heat transfer
- Adjoint-based receptivity and sensitivity analysis



# Stability research at CTR

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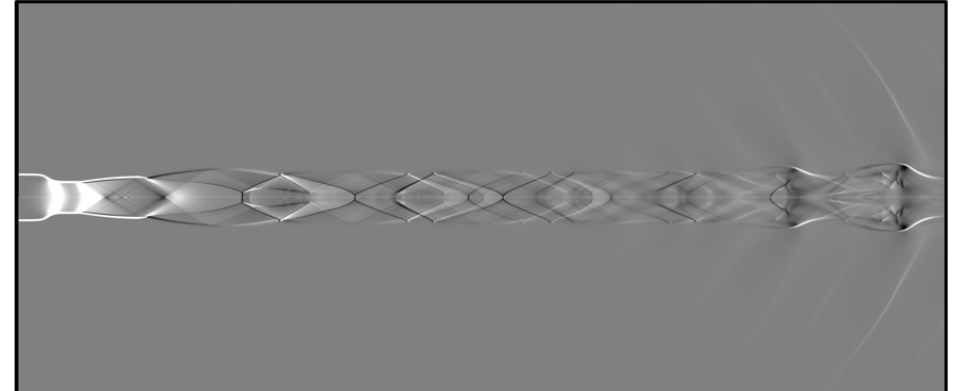
Nonlinear stability

Atomization

Reduced-order modeling

## Jet screech

- Critical phenomenon which reduces lifetime of jet engines
- Global stability analysis to identify mechanism of jet screech





# Stability research at CTR

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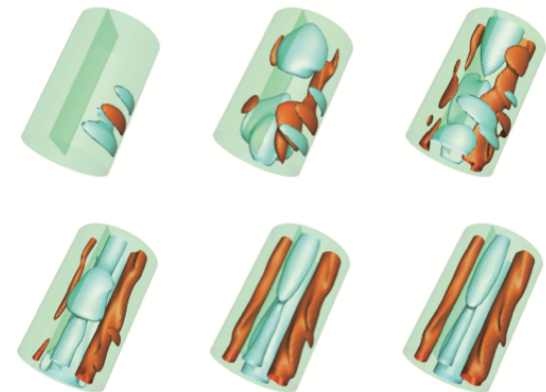
Nonlinear stability

Atomization

Reduced-order modeling

## Nonlinear optimal disturbances

- Classical linear stability theory valid in the limit of small perturbations
- Breakdown to turbulence results from strong nonlinear interactions



# Stability research at CTR

Flow separation

High-speed flows

Jet noise

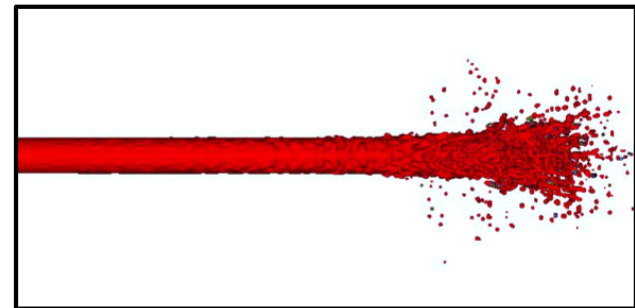
Nonlinear stability

Atomization

Reduced-order modeling

## Fragmentation of liquid jets

- Effective atomization of liquid jets critical in many applications
- Non-exponential mechanisms can lead to fragmentation



# Stability research at CTR

Flow separation

High-speed flows

Jet noise

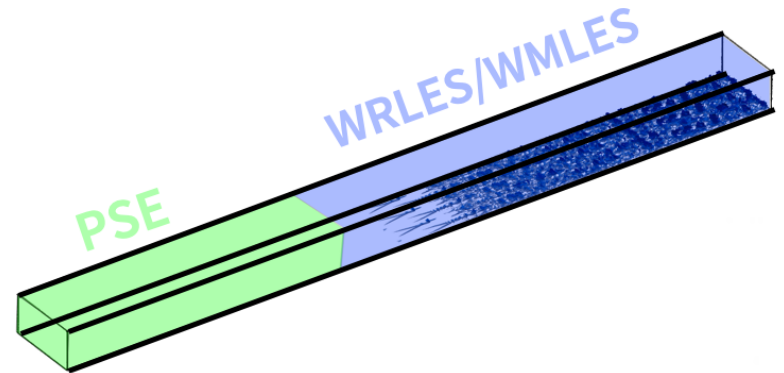
Nonlinear stability

Atomization

Reduced-order modeling

Reduced-order modeling of transitional flows:

- Accurate yet efficient model of transition to turbulence
- Physics-based formulation without tunable parameters



# Transition to turbulence



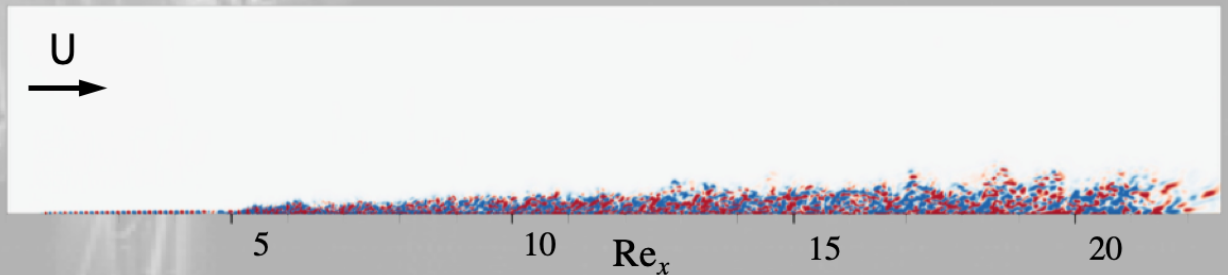
Transition to turbulence relevant for  
accurate estimation of drag and heat transfer

Stanford

# Transition to turbulence

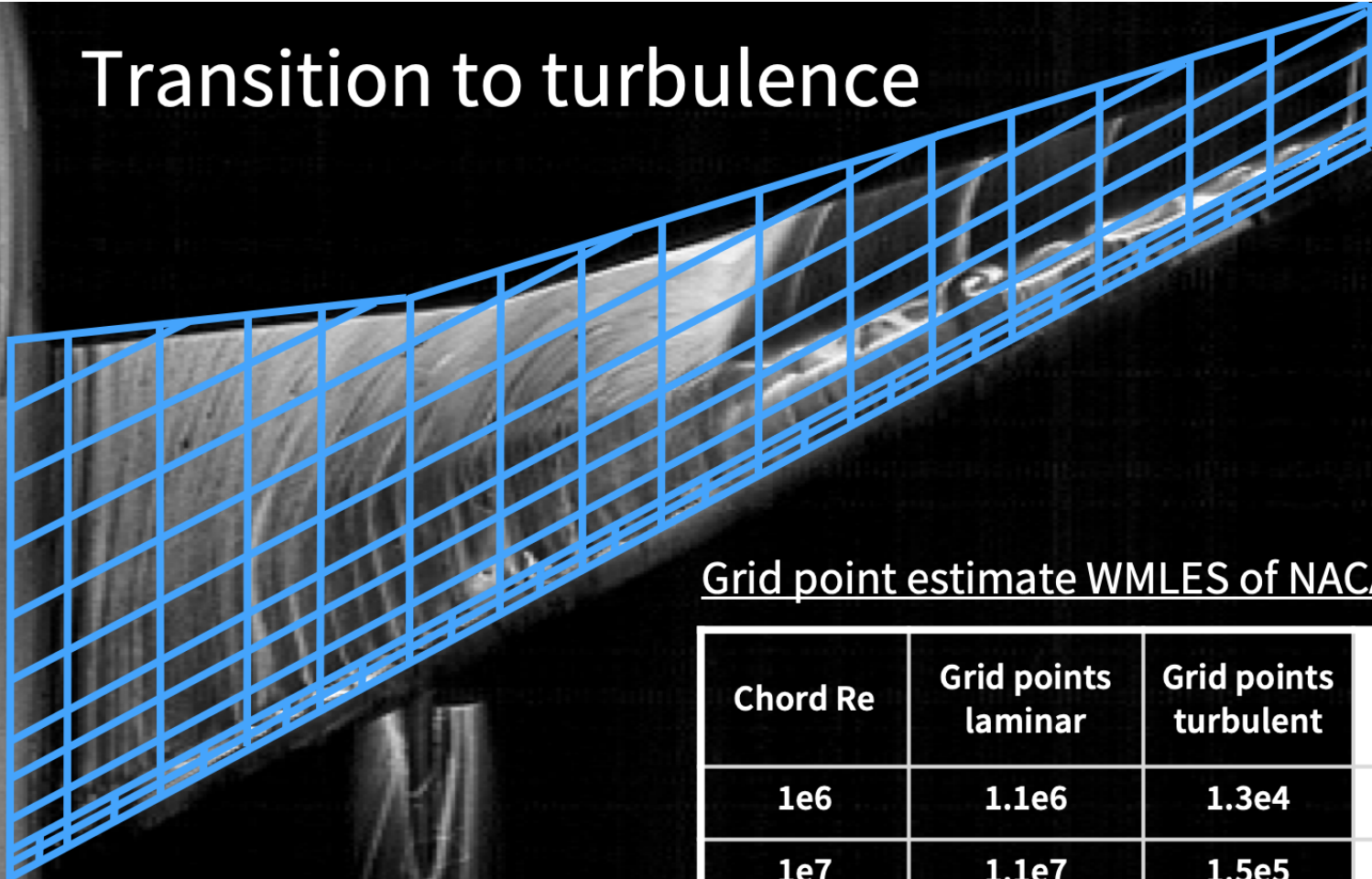
## LES of transitional boundary layer

*Park 2014*



*"In order to capture the correct streamwise growth of the disturbance waves, fine resolution is needed in the laminar region (otherwise the flow stays laminar)."*

# Transition to turbulence



Grid point estimate WMLES of NACA 0012

Chord Re	Grid points laminar	Grid points turbulent	Ratio
1e6	1.1e6	1.3e4	85
1e7	1.1e7	1.5e5	73
1e8	9.1e7	3.1e6	30

NASA CFD VISION 2030 (Slotnick *et al.* 2014)



# Transition to turbulence



→ Proper treatment of pre-transitional flow region in WMLES can require 10 to 100 times more points than in turbulent regime

*“Thus, we conclude that a key issue in the application of WMLES will be the modeling of the laminar and transitional region.”*

NASA CFD VISION 2030 (Slotnick et al. 2014)

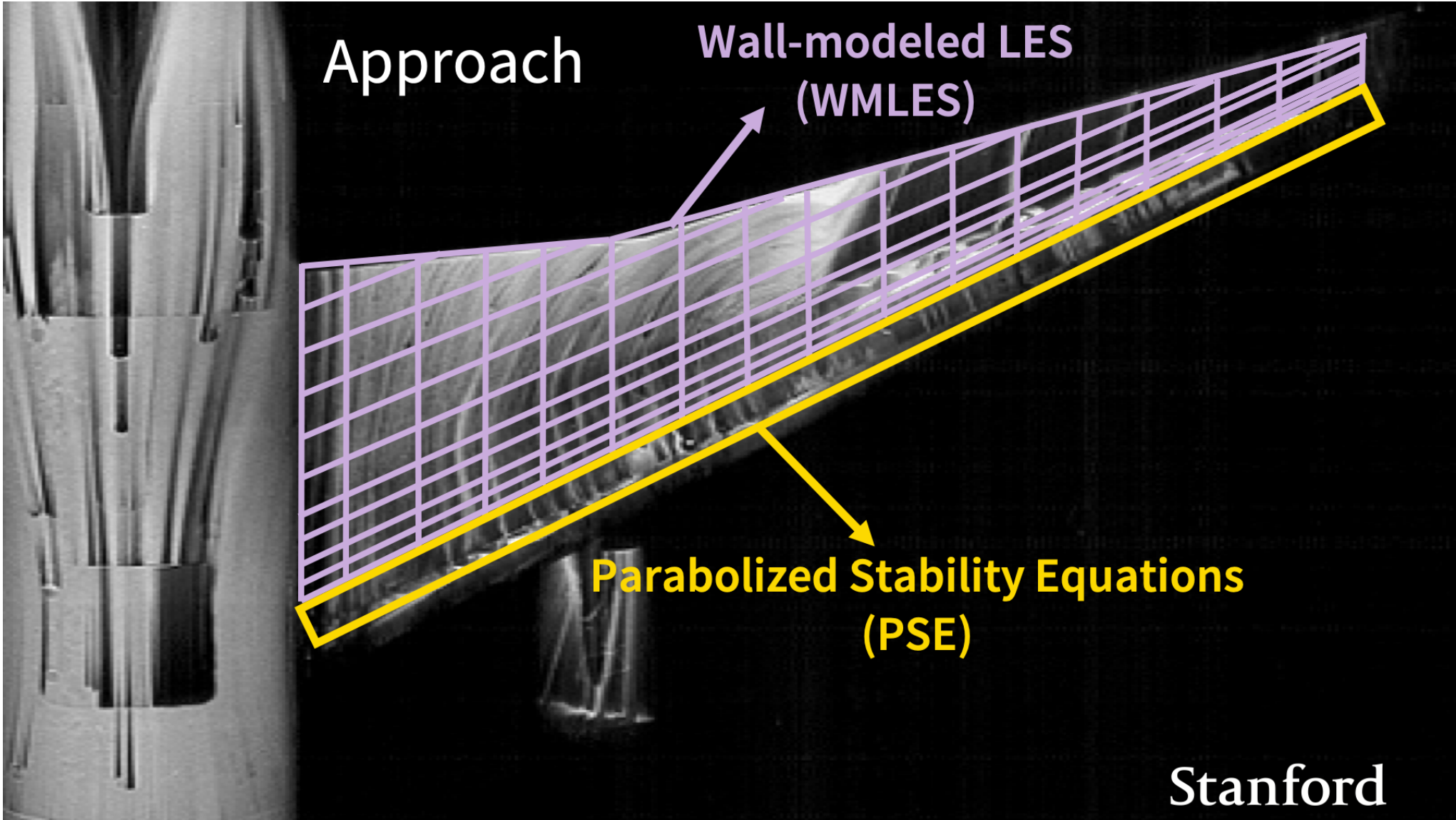


Approach

Wall-modeled LES  
(WMLES)

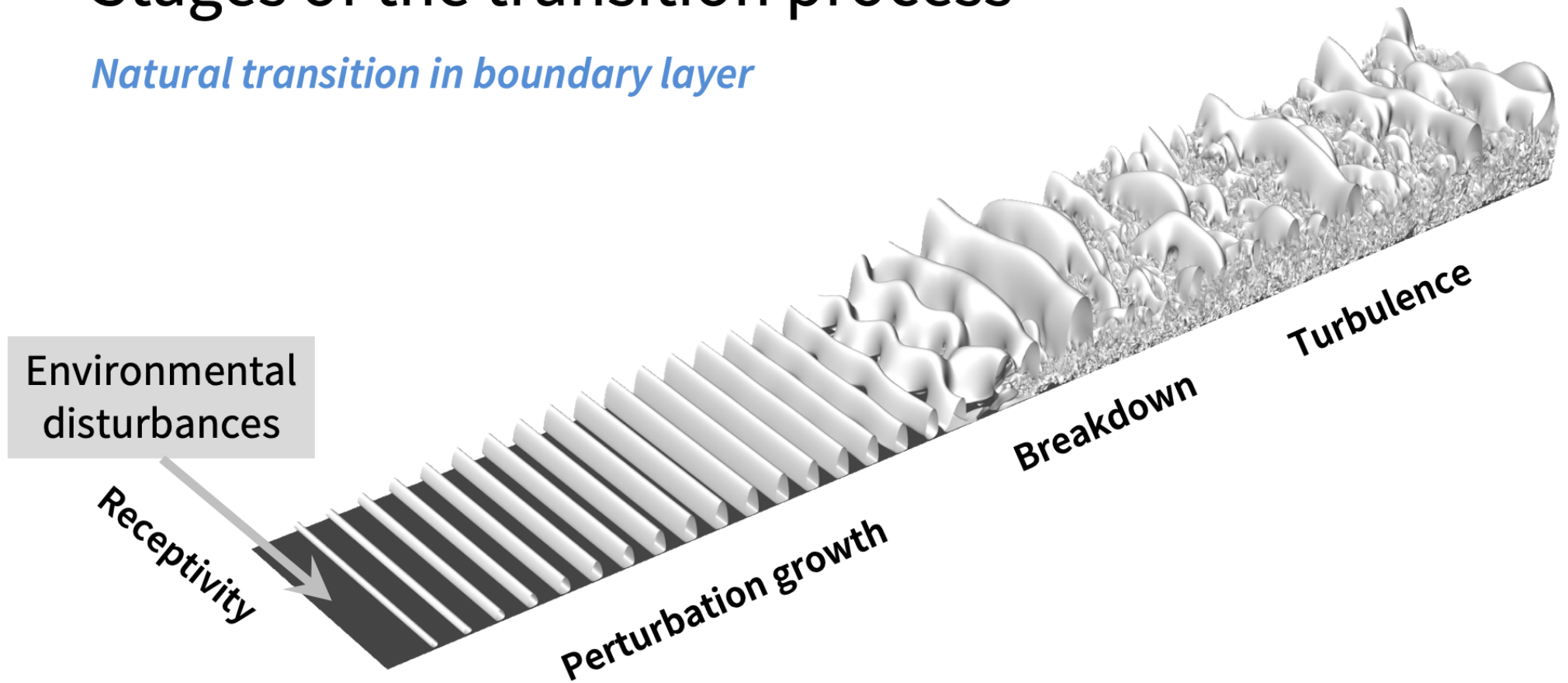
Parabolized Stability Equations  
(PSE)

Stanford



# Stages of the transition process

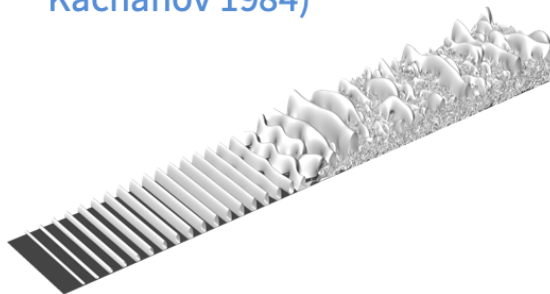
*Natural transition in boundary layer*



# Transition scenarios

## NATURAL

- Low levels of external disturbances
- Exponential amplification of primary disturbances (TS waves)
- Classical configurations: H/K-type (Herbert 1988, Kachanov 1984)



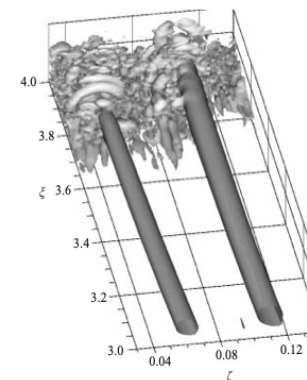
## BYPASS

- Moderate levels of external disturbances
- Algebraic amplification of primary disturbances (streaks)
- Exponential secondary instability



## CROSSFLOW

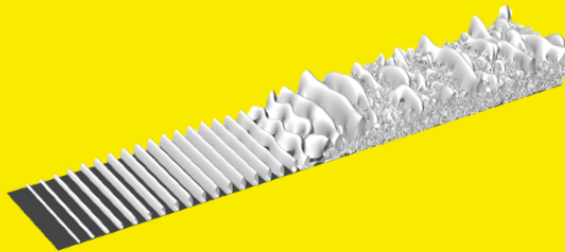
- Inflectional (exponential) primary disturbance
- Rapid breakdown to turbulence



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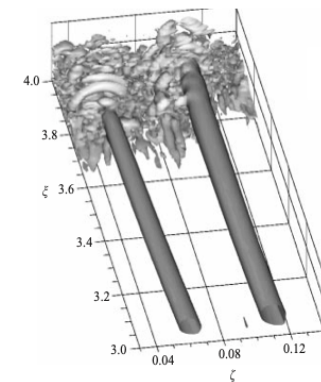
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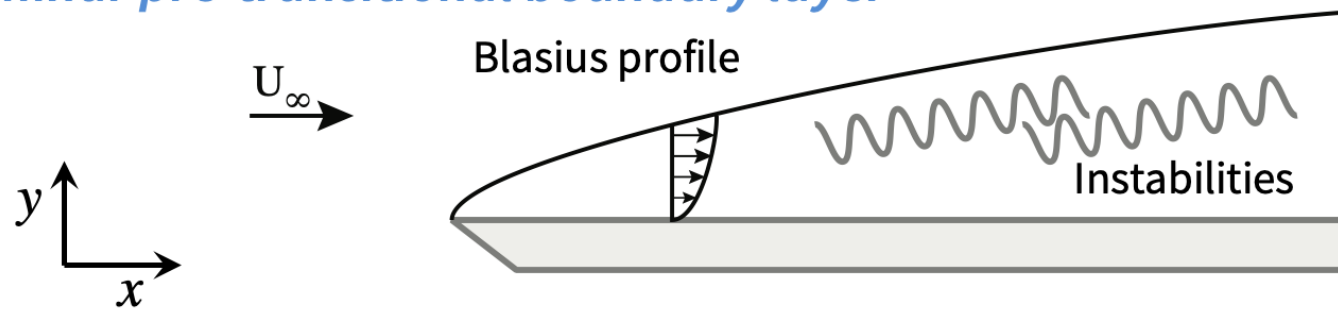
- Inflectional (exponential) primary disturbance
- Rapid breakdown to turbulence



# Parabolized Stability Equations

(Herbert 1992)

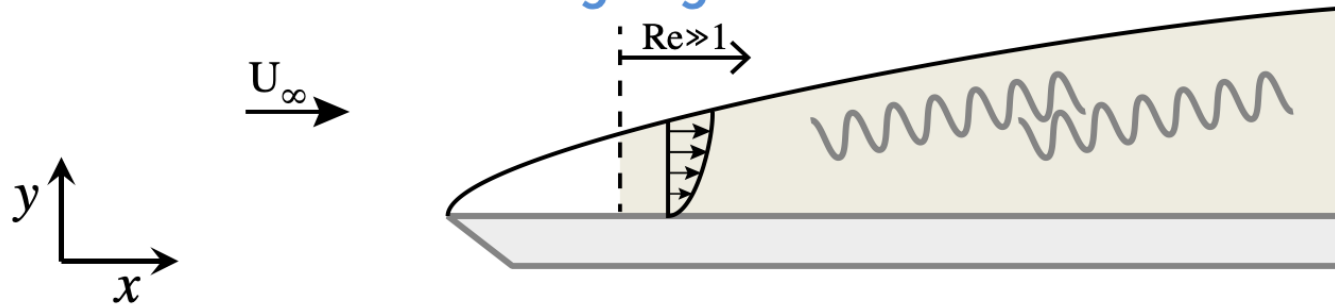
*Laminar pre-transitional boundary layer*



# Parabolized Stability Equations

(Herbert 1992)

*Sufficient distance to leading edge*

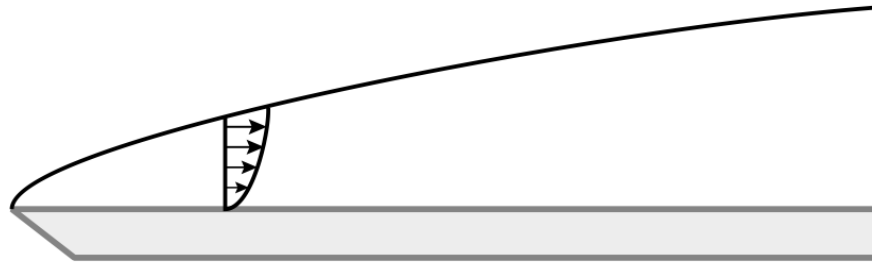


# Parabolized Stability Equations

## *Separation of the state*

**Base**

$$\bar{\mathbf{q}}(x, y) = (\bar{u}, \bar{v}, \bar{w}, \bar{p})^T$$



**Perturbations**

+



$$\mathbf{q}'(x, y, z, t) = (u', v', w', p')^T$$

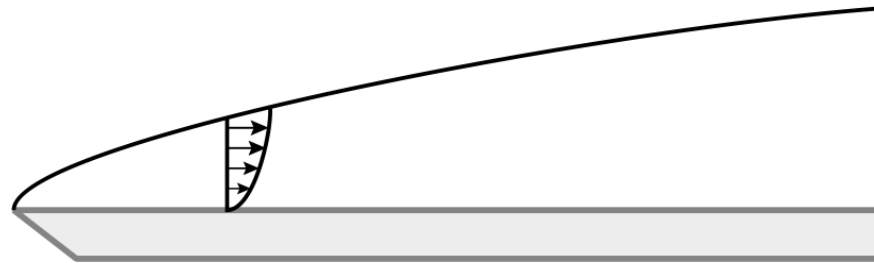


# Parabolized Stability Equations

## *Separation of the perturbations*

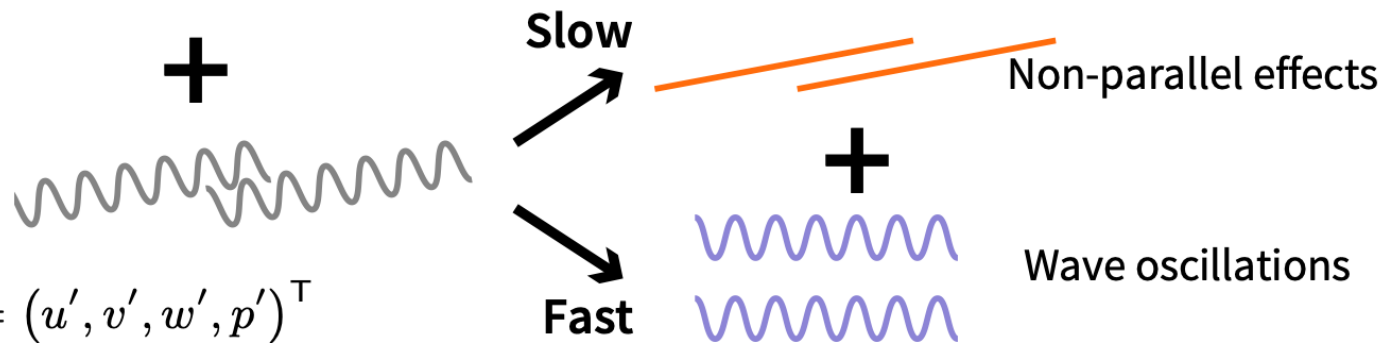
**Base**

$$\bar{\mathbf{q}}(x, y) = (\bar{u}, \bar{v}, \bar{w}, \bar{p})^T$$



**Perturbations**

$$\mathbf{q}'(x, y, z, t) = (u', v', w', p')^T$$

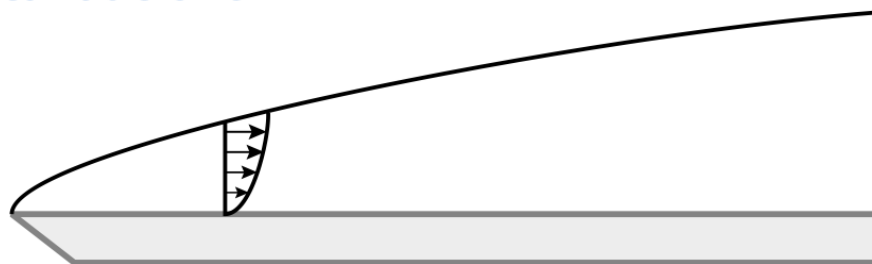


# Parabolized Stability Equations

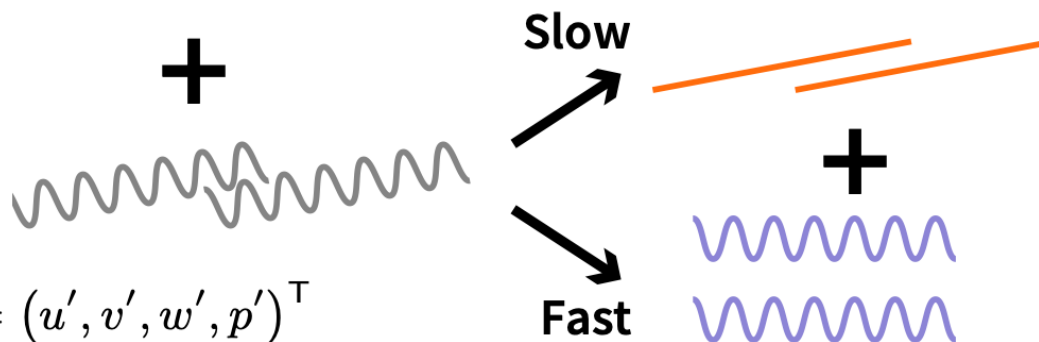
## Separation of the perturbations

Base

$$\bar{\mathbf{q}}(x, y) = (\bar{u}, \bar{v}, \bar{w}, \bar{p})^T$$



Perturbations



$$\mathbf{q}'(x, y, z, t) = (u', v', w', p')^T$$

Ansatz:  $\mathbf{q}'(x, y, z, t) = \hat{\mathbf{q}}(x, y) \exp(i(\beta z + \omega t)) \exp\left(i \int_{x_0}^x \alpha(\xi) d\xi\right)$

Subject to

$$\frac{\partial}{\partial x} \int_0^\infty \hat{\mathbf{q}}^H \hat{\mathbf{q}} dy = 0$$

# Parabolized Stability Equations

## Derivation

$$\mathbf{q}'(x, y, z, t) = \hat{\mathbf{q}}(x, y) \exp(i(\beta z + \omega t)) \exp\left(i \int_{x_0}^x \alpha(\xi) d\xi\right)$$

Navier-Stokes

$\mathcal{O}(Re^{-1})$

Parabolized Stability Equations (PSE)

# Parabolized Stability Equations

For the  $n^{\text{th}}$  harmonic in span and the  $m^{\text{th}}$  harmonic in time:

$$\mathbf{A}\hat{\mathbf{q}}_{n,m} + \mathbf{B}\frac{\partial\hat{\mathbf{q}}_{n,m}}{\partial y} + \mathbf{C}\frac{\partial^2\hat{\mathbf{q}}_{n,m}}{\partial y^2} + \mathbf{D}\frac{\partial\hat{\mathbf{q}}_{n,m}}{\partial x} = \hat{\mathbf{F}}_{n,m}$$

Nonlinear coupling of harmonics

with

$$\mathbf{A} = \begin{bmatrix} r + \frac{\partial U}{\partial x} & \frac{\partial U}{\partial y} & 0 & i\alpha \\ 0 & r + \frac{\partial V}{\partial y} & 0 & 0 \\ \frac{\partial W}{\partial x} & \frac{\partial W}{\partial y} & r & in\beta \\ i\alpha & 0 & in\beta & 0 \end{bmatrix},$$

$$\mathbf{C} = \begin{bmatrix} -\frac{1}{Re} & 0 & 0 & 0 \\ 0 & -\frac{1}{Re} & 0 & 0 \\ 0 & 0 & -\frac{1}{Re} & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix},$$

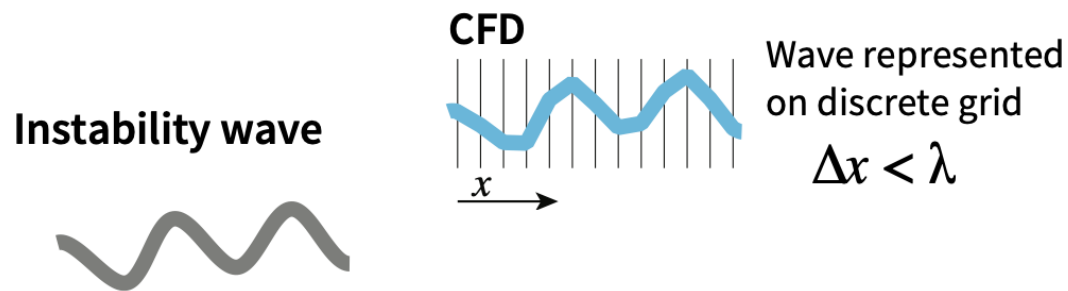
where  $r = -im\omega + i\alpha_{n,m}U + in\beta W + \frac{1}{Re}(\alpha_{n,m}^2 + n^2\beta^2)$

$$\mathbf{B} = \begin{bmatrix} V & 0 & 0 & 0 \\ 0 & V & 0 & 1 \\ 0 & 0 & V & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix},$$

$$\mathbf{D} = \begin{bmatrix} U & 0 & 0 & 1 \\ 0 & U & 0 & 0 \\ 0 & 0 & U & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix},$$

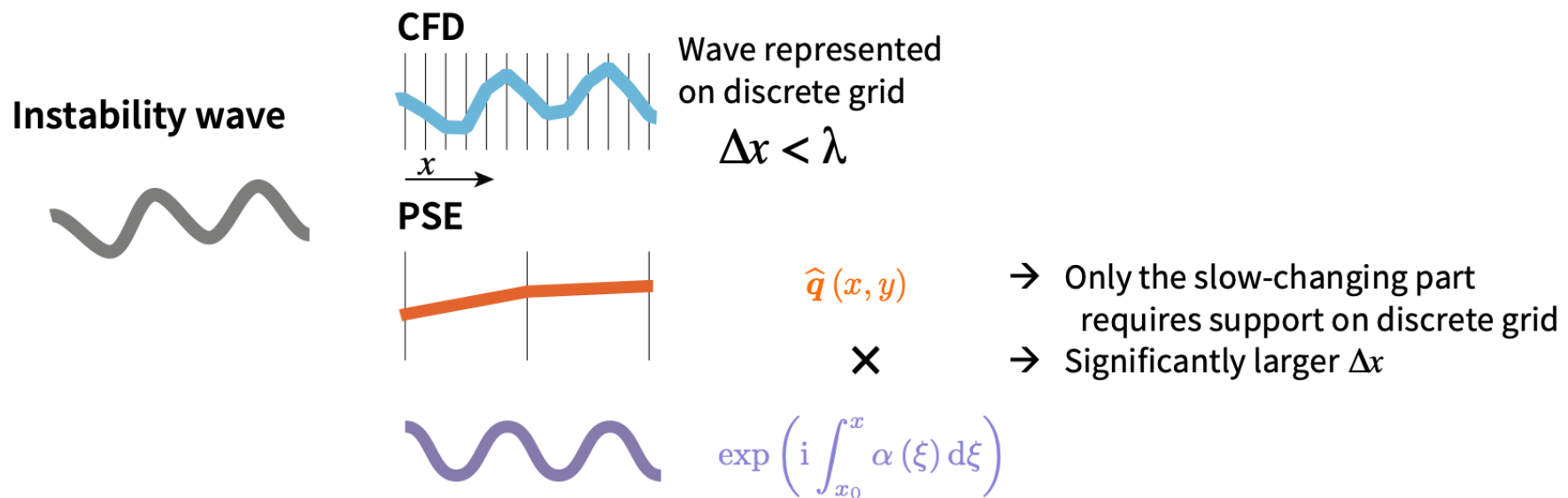
# Parabolized Stability Equations

## *Comparison to CFD*



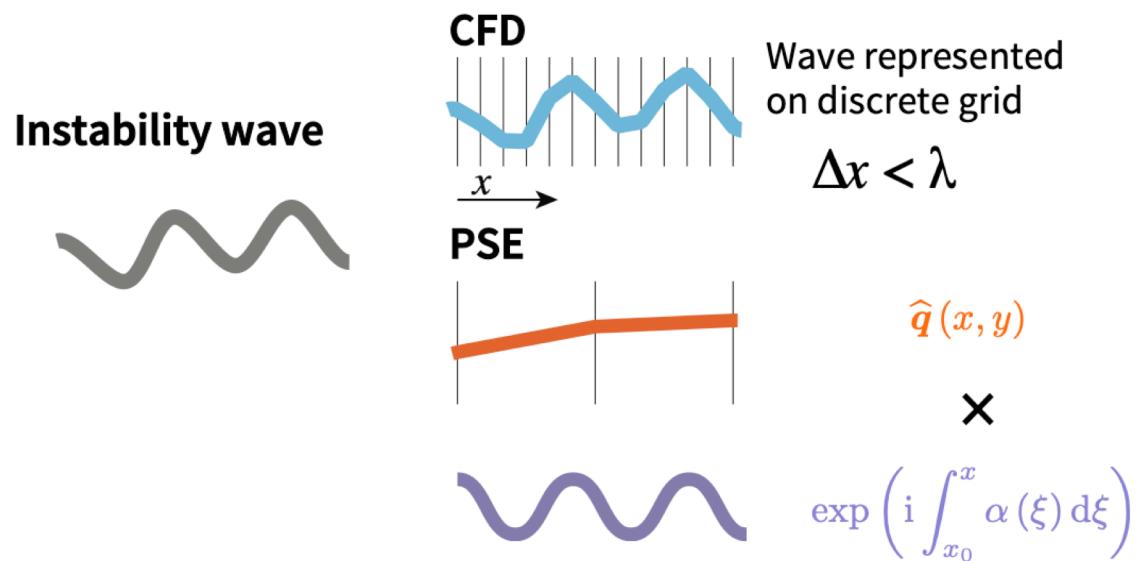
# Parabolized Stability Equations

## Comparison to CFD



# Parabolized Stability Equations

## Comparison to CFD



	CFD	PSE
Time	Integration	Limited harmonic expansion
Span	FD/FV/Spectral	Limited harmonic expansion
Normal	FD/FV/Spectral	Spectral
Pressure	2D/3D ellipticity	1D ellipticity

→ PSE offer substantial computational savings



# Parabolized Stability Equations

## *Capabilities*

### Compatible with

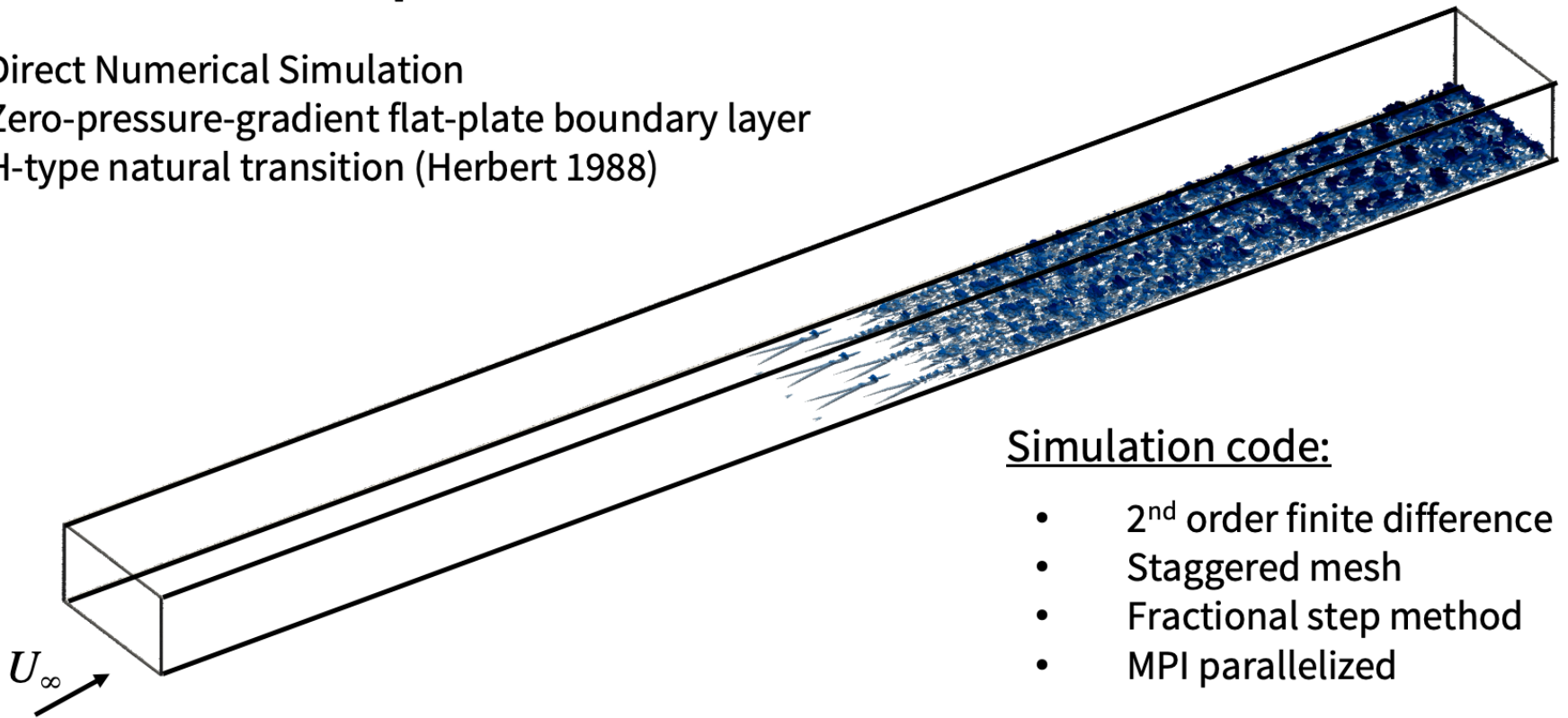
- Growth of exponential instabilities
- Nonparallel effects (boundary layer growth)
- Nonlinear effects (mode interaction)
- Three-dimensional flows (swept wings)
- Moderate surface curvature (attached flow)
- Moderate pressure gradient

### Incompatible with

- Unsteady flows
- Flows at low  $Re$ , including leading edges
- Separation/recirculation
- Turbulence, including local spots

# Numerical experiments

- Direct Numerical Simulation
- Zero-pressure-gradient flat-plate boundary layer
- H-type natural transition (Herbert 1988)



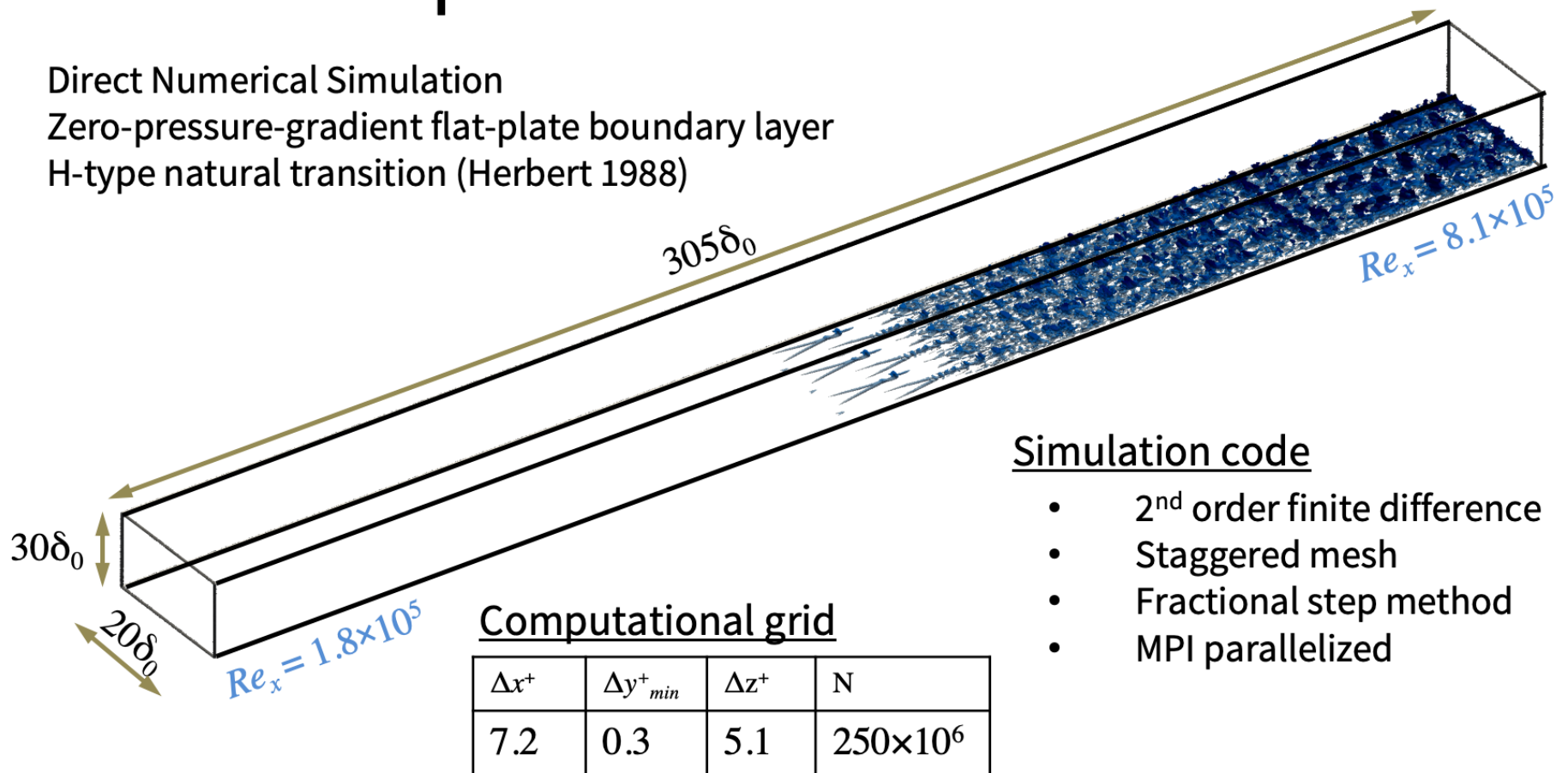
## Simulation code:

- 2<sup>nd</sup> order finite difference
- Staggered mesh
- Fractional step method
- MPI parallelized

Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)

# Numerical experiments

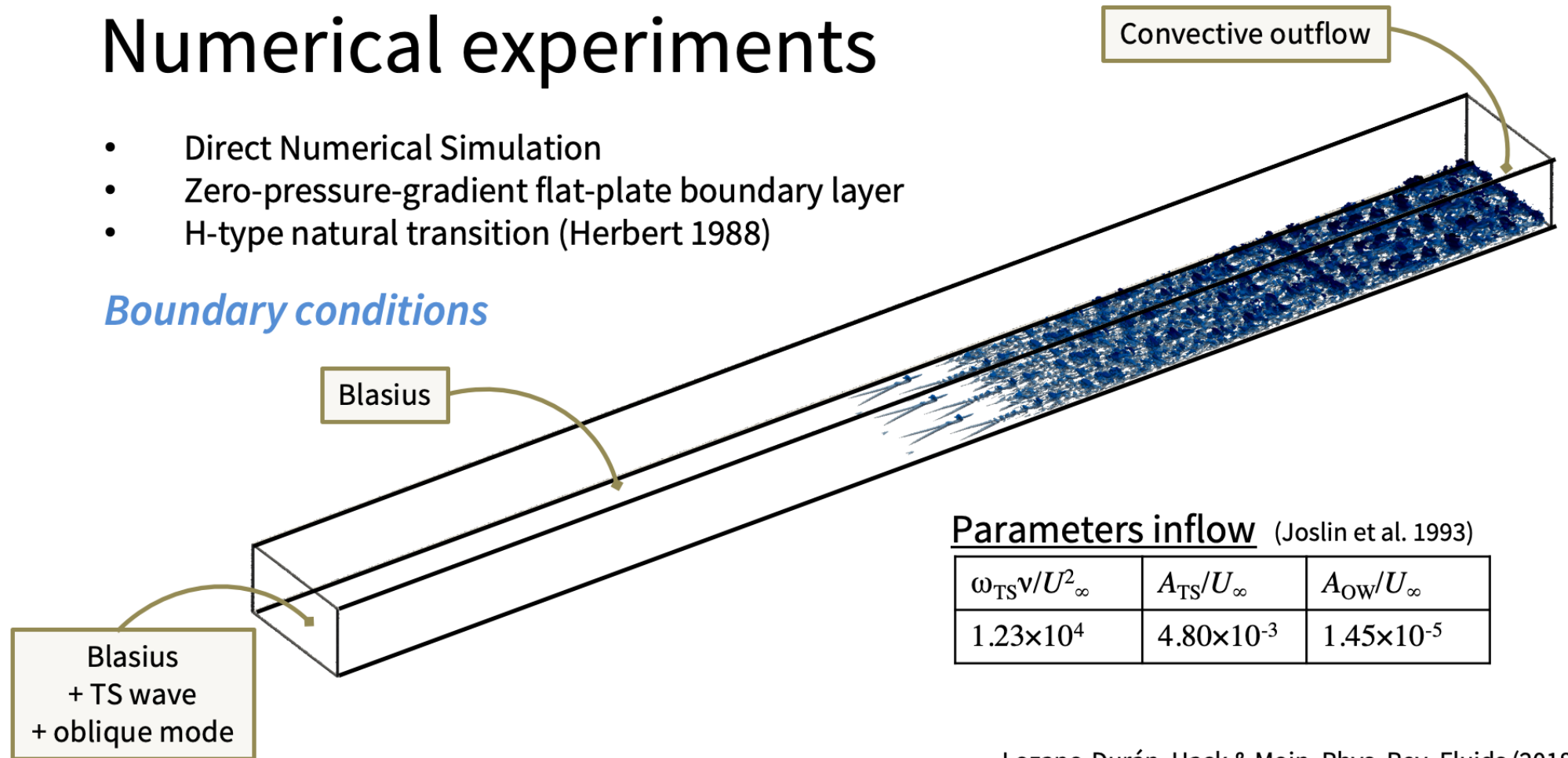
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# Numerical experiments

- Direct Numerical Simulation
- Zero-pressure-gradient flat-plate boundary layer
- H-type natural transition (Herbert 1988)

## Boundary conditions



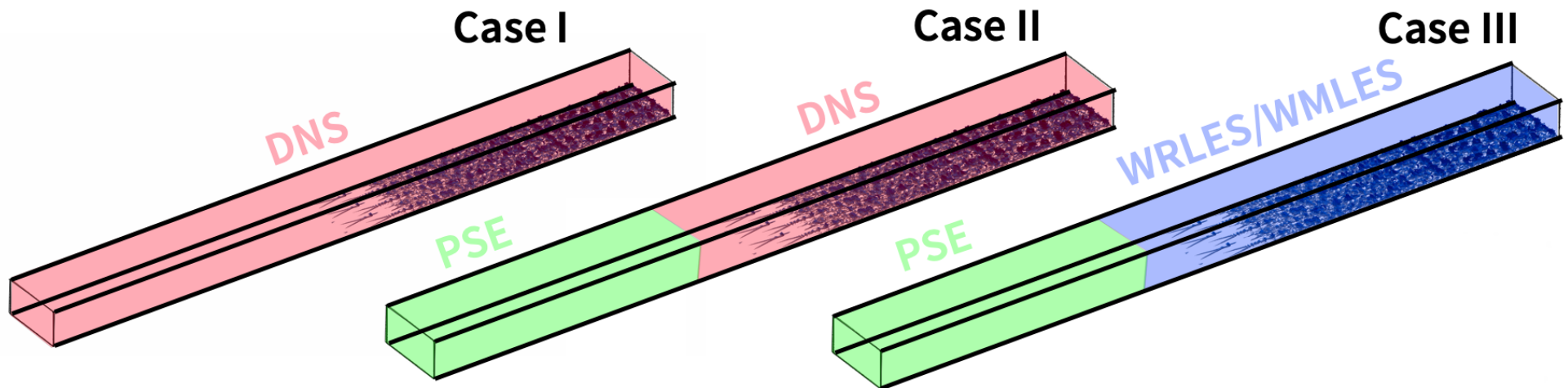
## Parameters inflow (Joslin et al. 1993)

$\omega_{TS} \nu / U_\infty^2$	$A_{TS} / U_\infty$	$A_{OW} / U_\infty$
$1.23 \times 10^4$	$4.80 \times 10^{-3}$	$1.45 \times 10^{-5}$

Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)

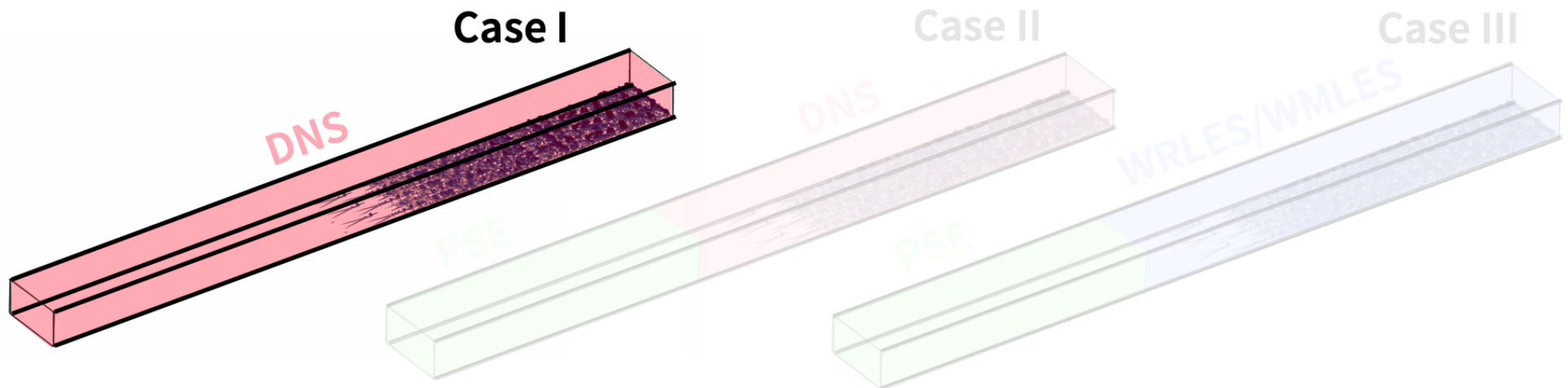
# Numerical experiments

*Considered setups*



# Numerical experiments

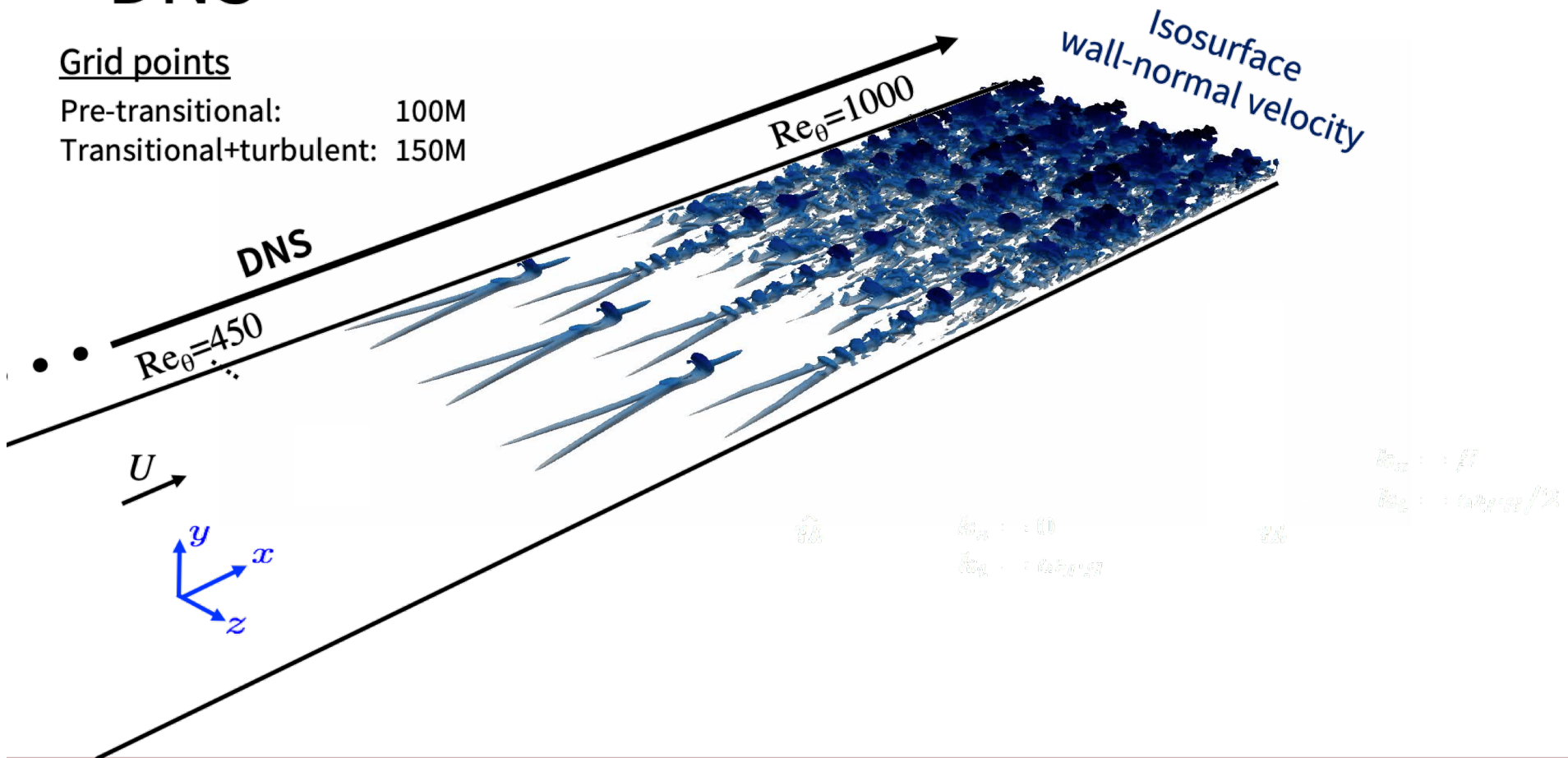
## *Considered setups*



# DNS

## Grid points

Pre-transitional: 100M  
Transitional+turbulent: 150M

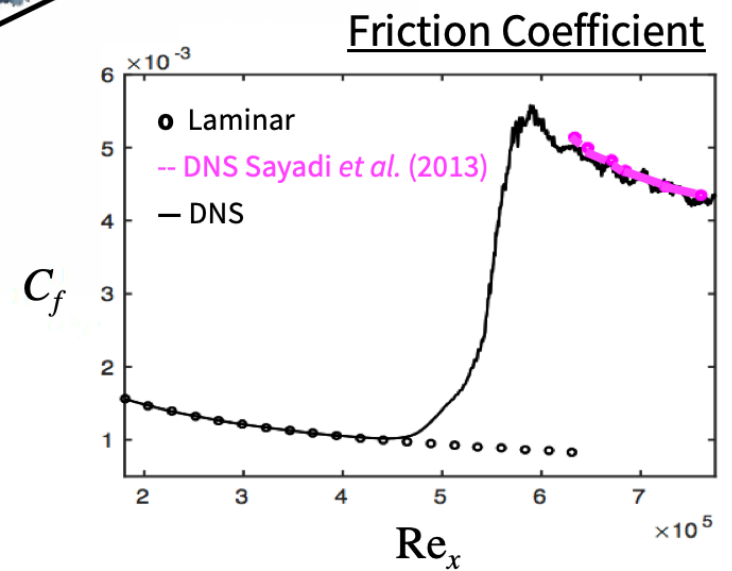
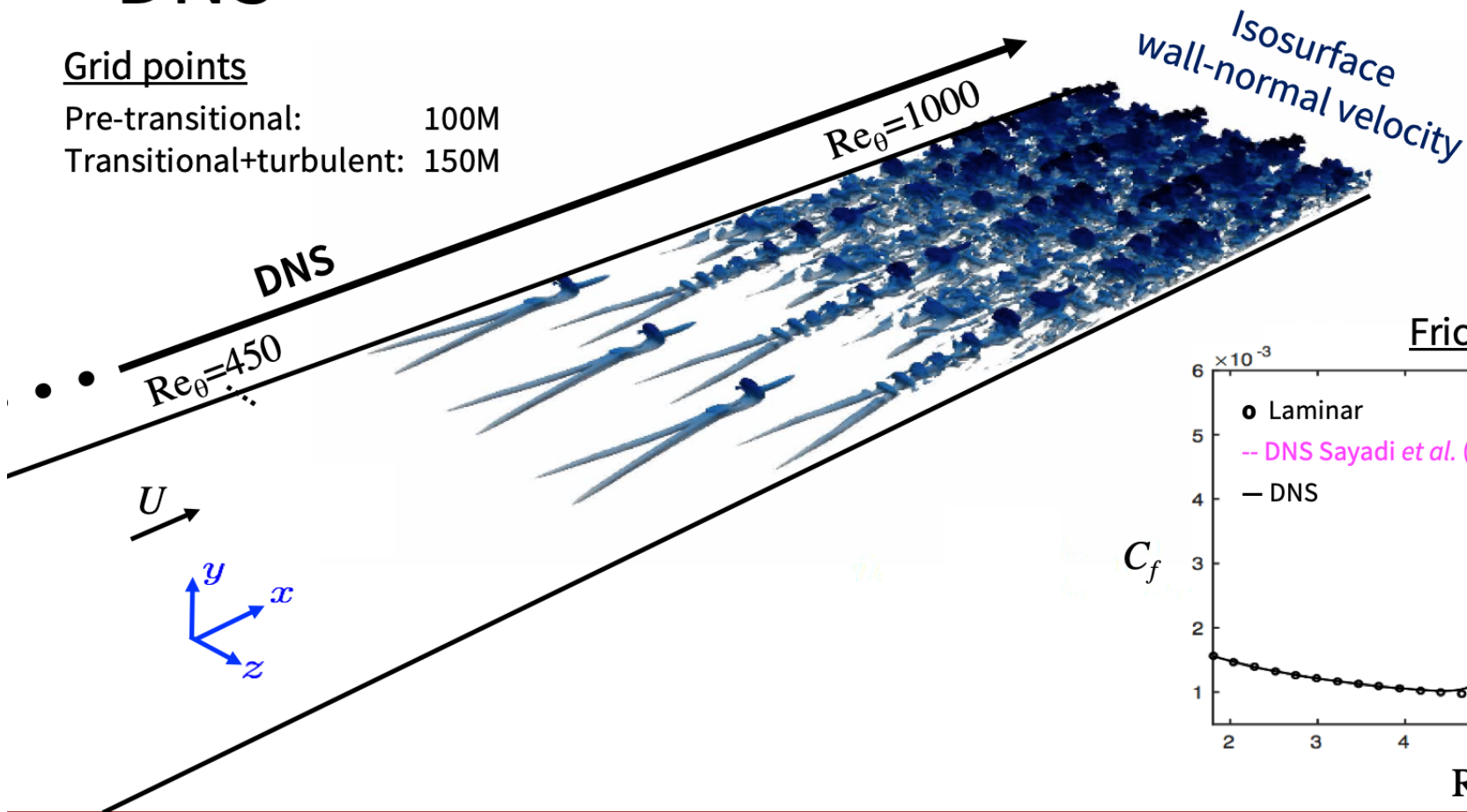




# DNS

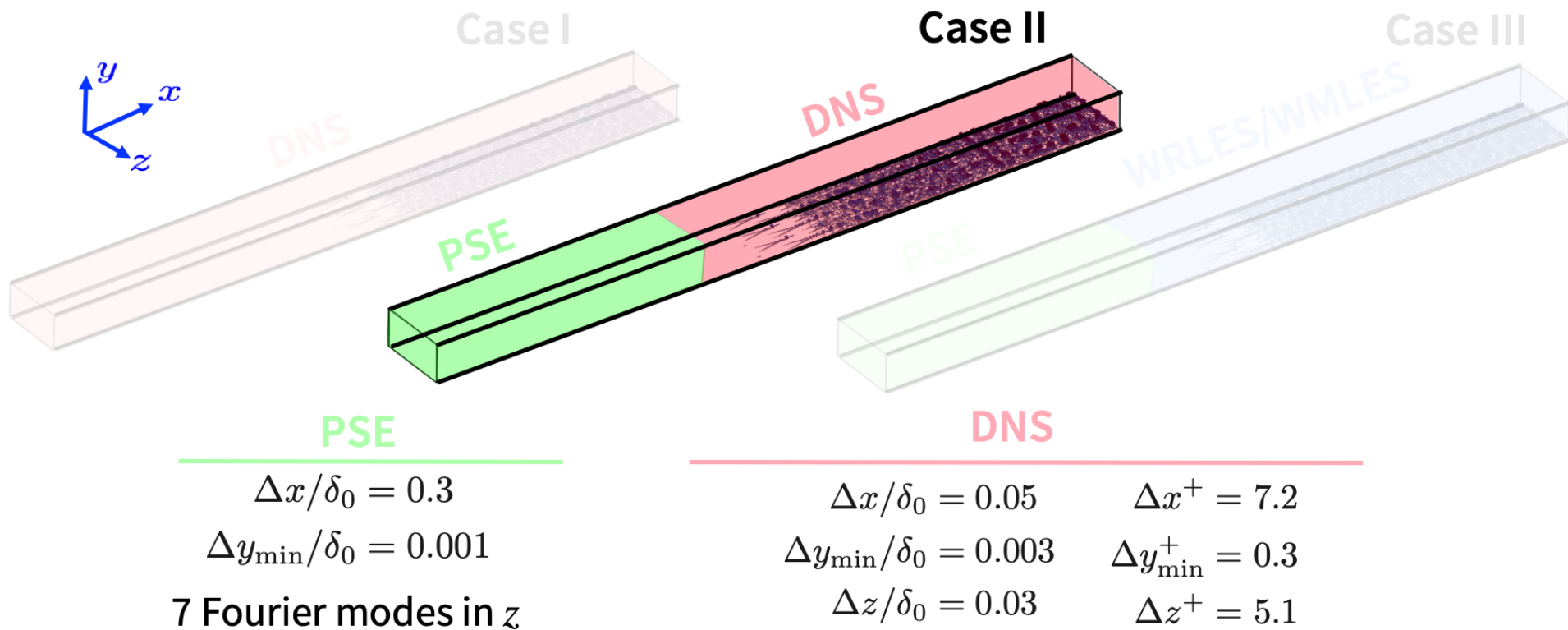
## Grid points

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Transitional+turbulent: 150M



# Numerical experiments

## Considered setups

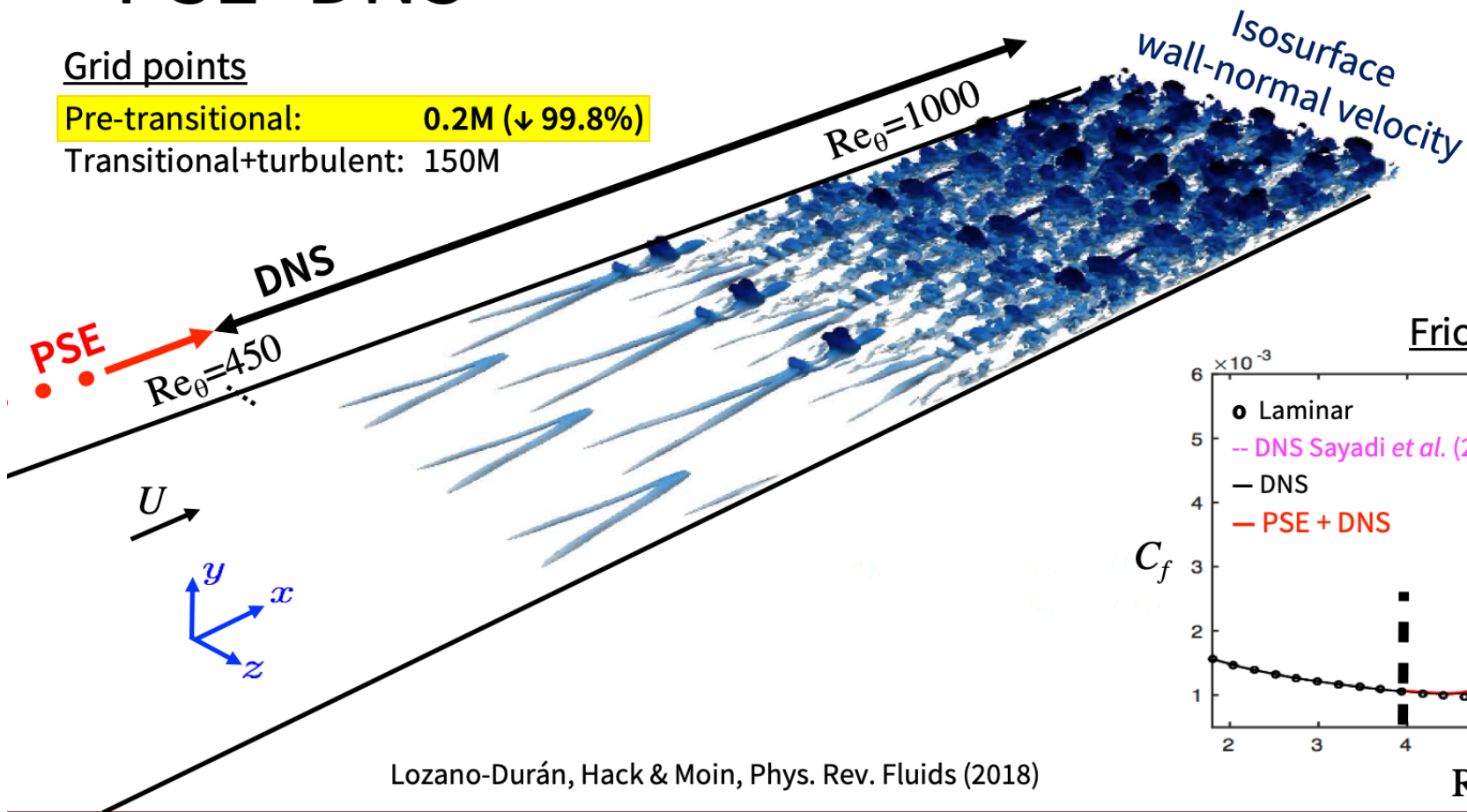


# PSE+DNS

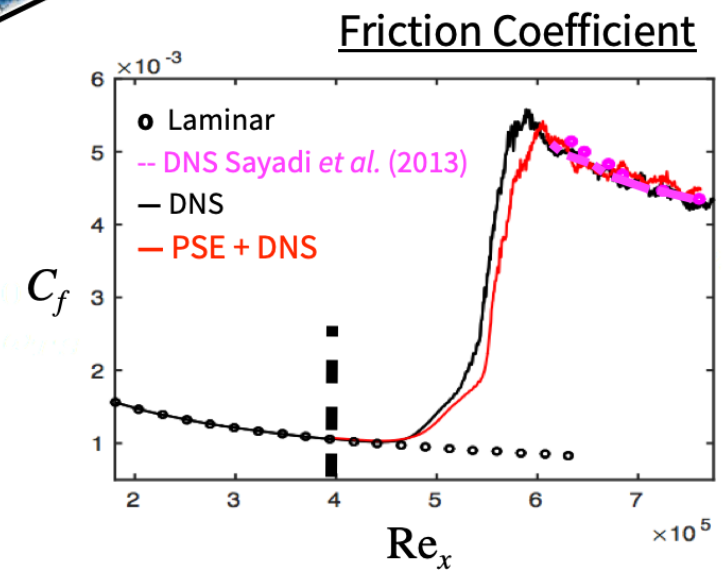
Grid points

Pre-transitional: 0.2M ( $\downarrow$  99.8%)

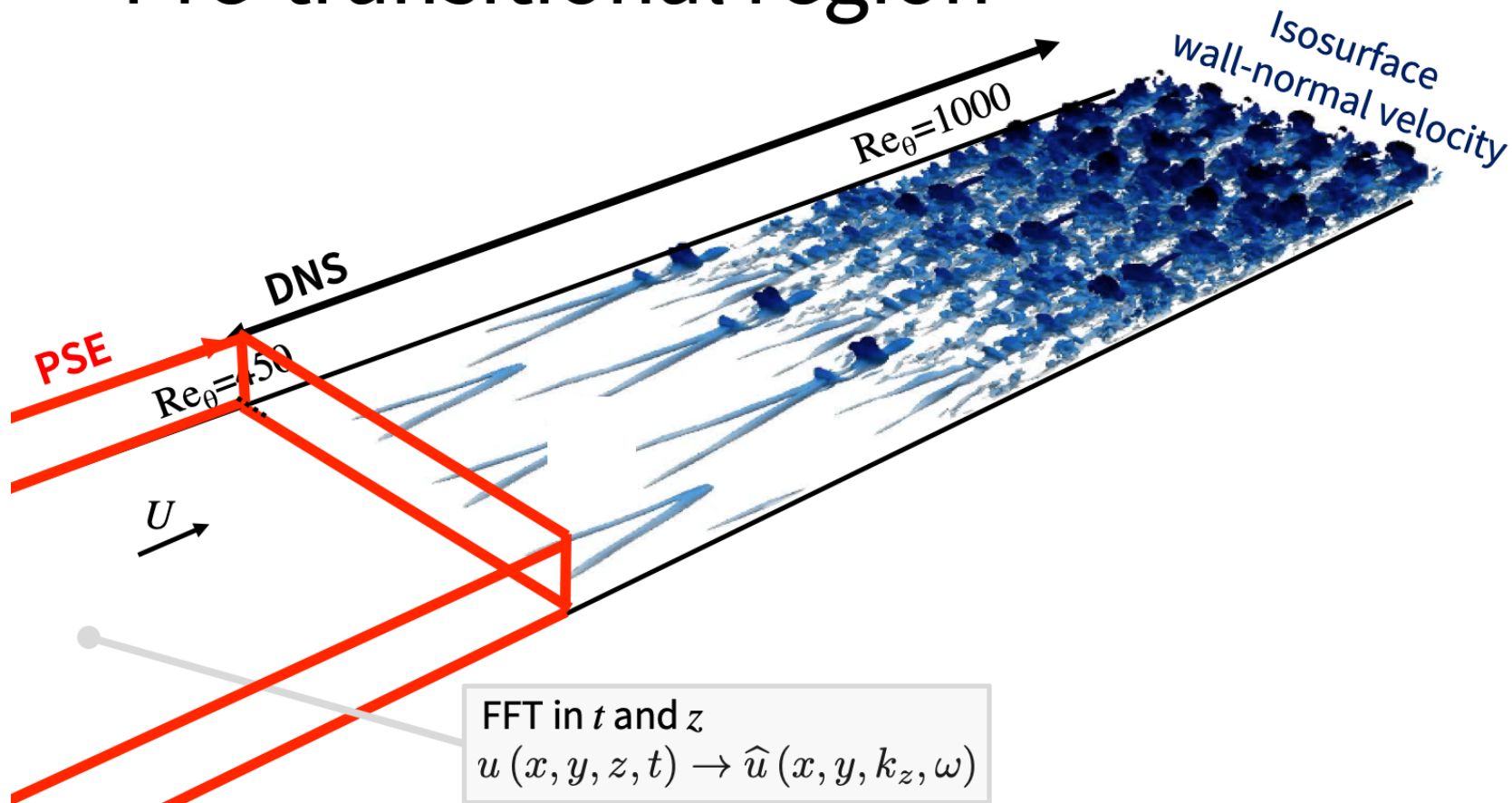
Transitional+turbulent: 150M



Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)

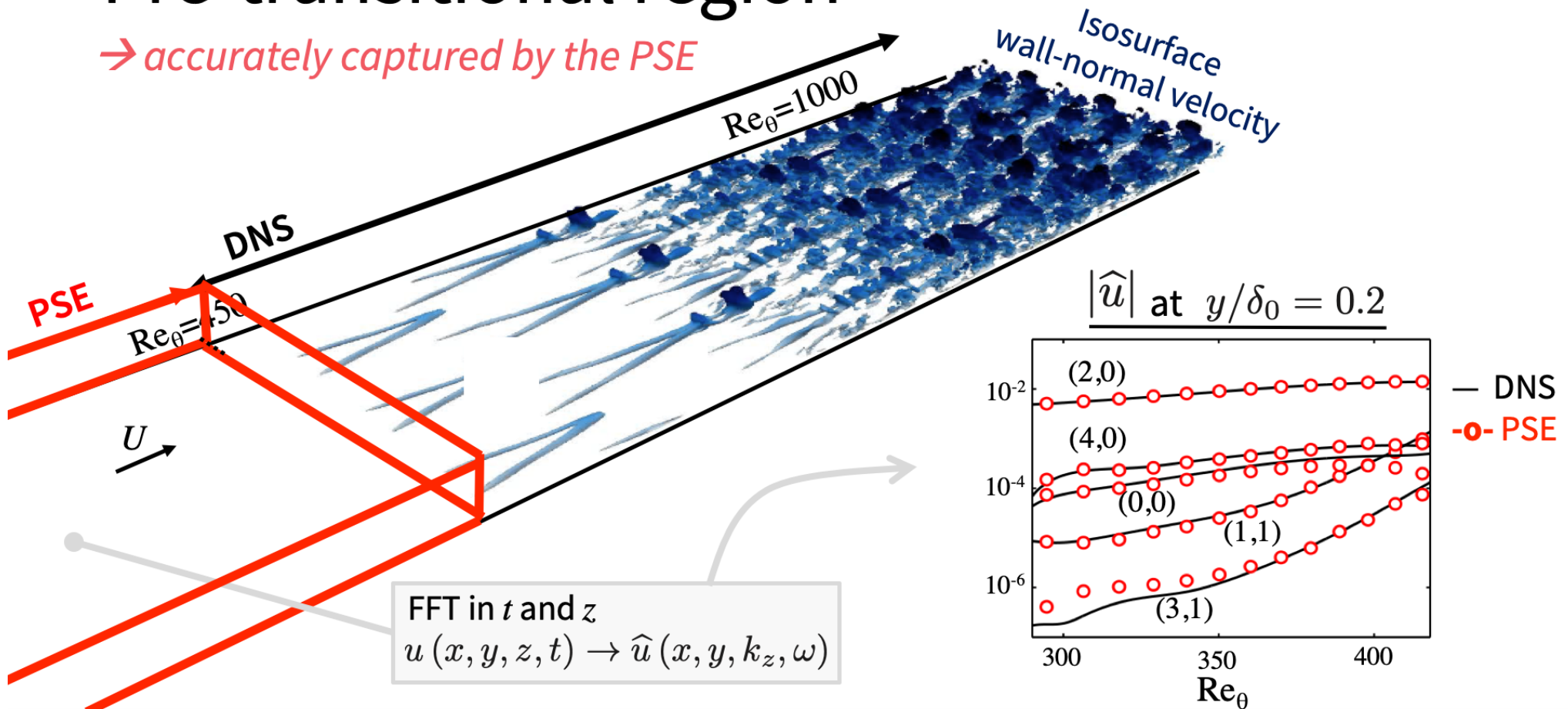


# Pre-transitional region



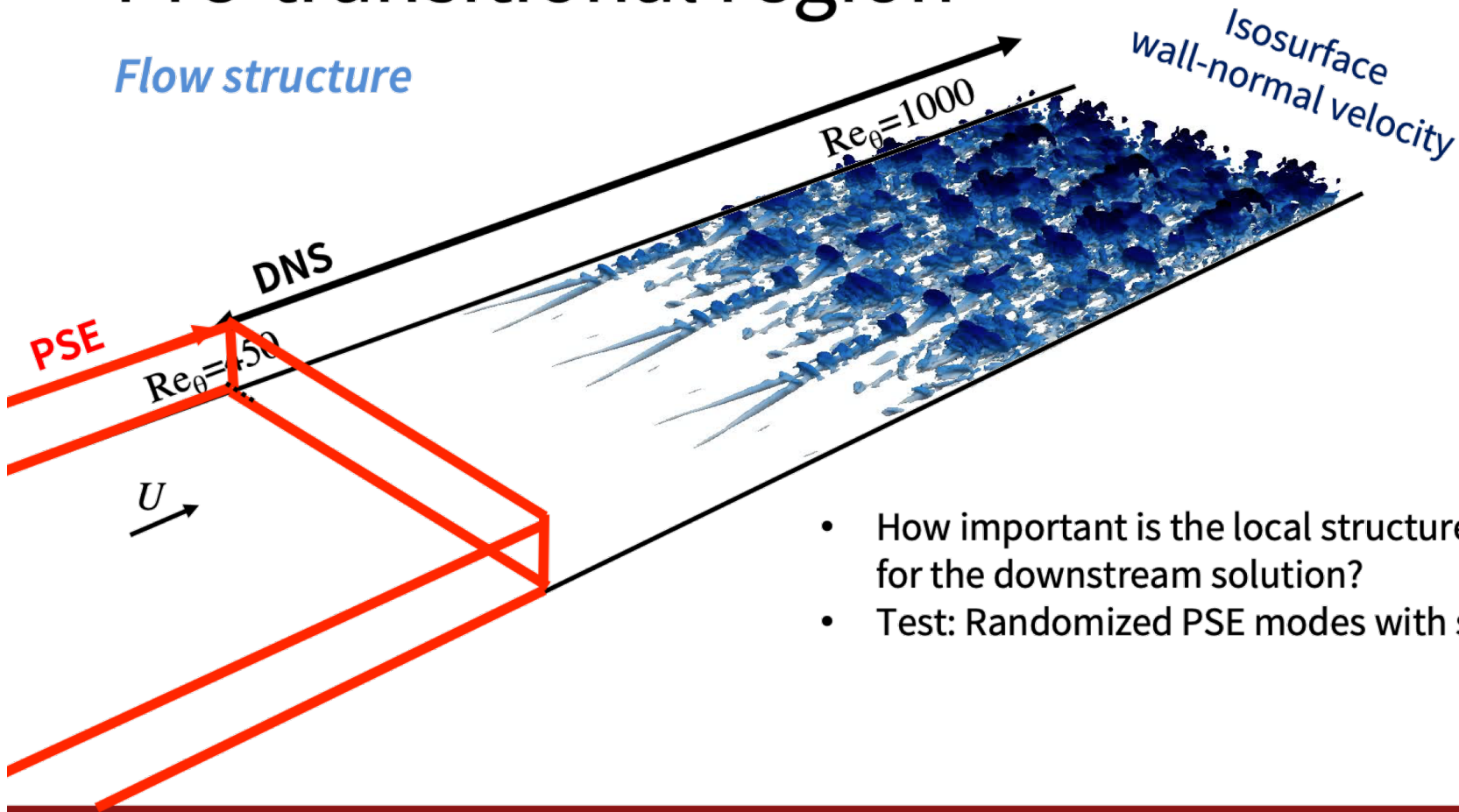
# Pre-transitional region

→ accurately captured by the PSE



# Pre-transitional region

*Flow structure*

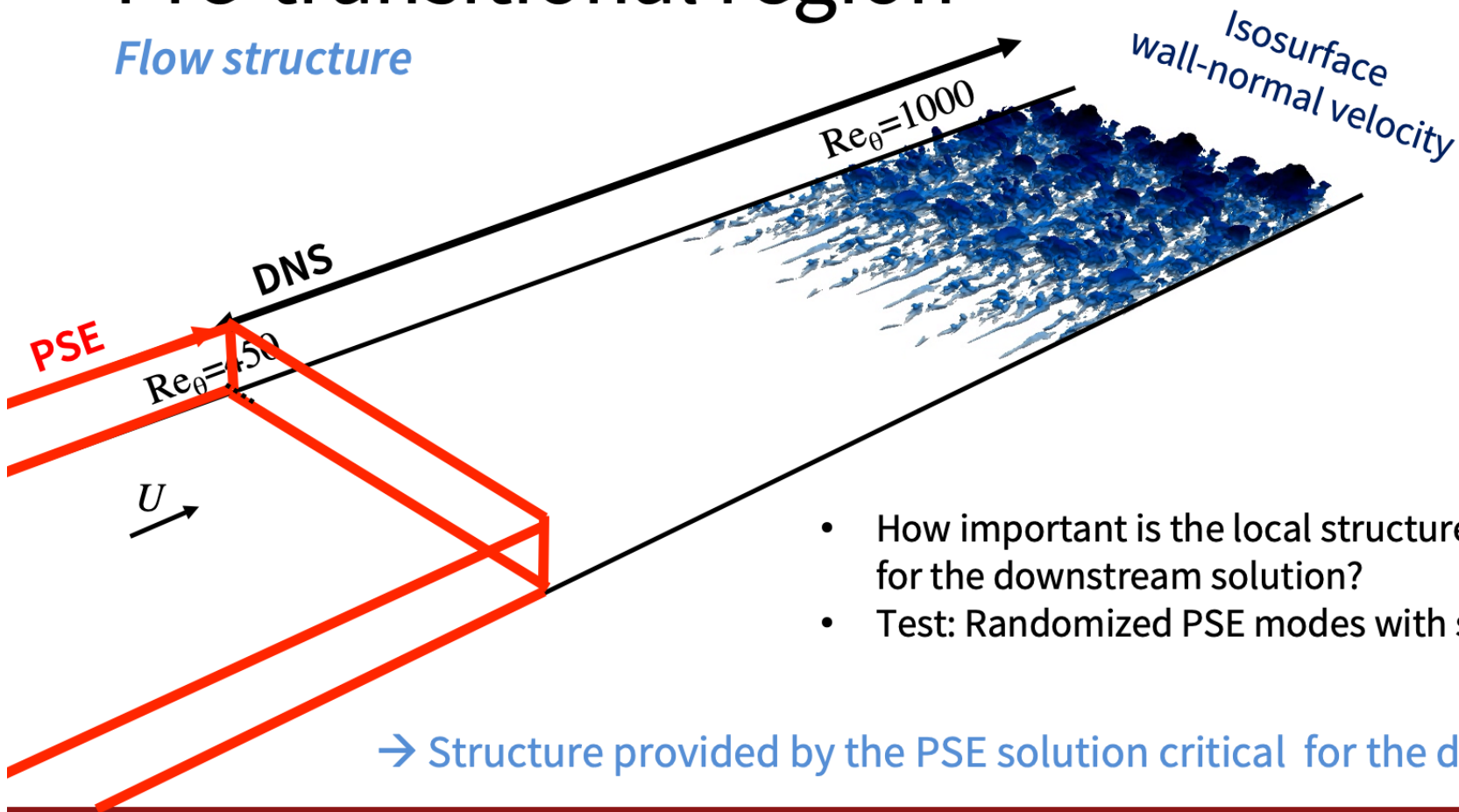


- How important is the local structure of the flow for the downstream solution?
- Test: Randomized PSE modes with same total energy



# Pre-transitional region

*Flow structure*

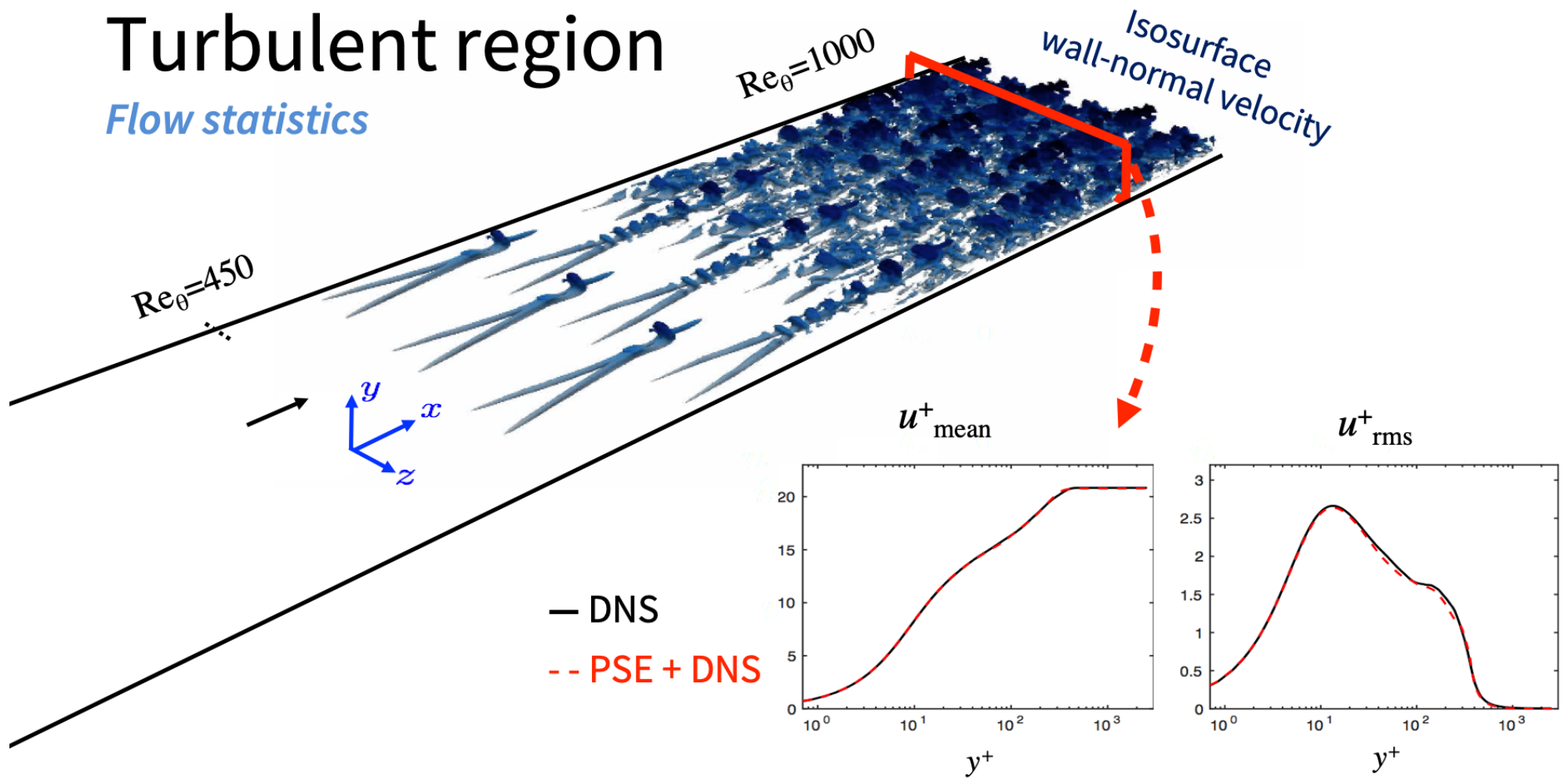


- How important is the local structure of the flow for the downstream solution?
- Test: Randomized PSE modes with same total energy

→ Structure provided by the PSE solution critical for the downstream flow

# Turbulent region

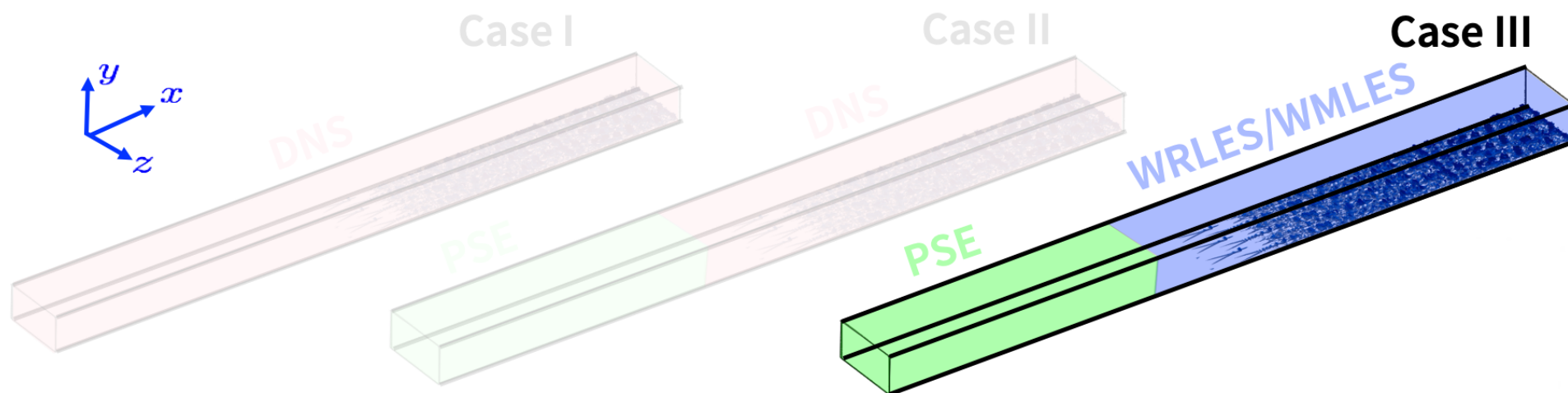
*Flow statistics*





# Numerical experiments

## Considered setups



### PSE

$$\Delta x / \delta_0 = 0.3$$

$$\Delta y_{\min} / \delta_0 = 0.001$$

7 Fourier modes in  $z$

### WRLES

$$\Delta x / \delta_0 = 0.31$$

$$\Delta y_{\min} = 0.010$$

$$\Delta z / \delta_0 = 0.13$$

$$\Delta x^+ = 45$$

$$\Delta y_{\min}^+ = 1$$

$$\Delta z^+ = 22$$

### WMLES

$$\Delta x^+ = 45$$

$$\Delta y_{\min}^+ = 18$$

$$\Delta z^+ = 22$$

# Large-eddy simulation

- Dynamic Smagorinsky SGS model**

*Germano et al., Phys. Fluids 1991; Lilly, Phys. Fluids 1992*

SGS stress closure:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = 2C\Delta^2|\bar{S}|\bar{S}_{ij}$$

based on large-scale strain  $\bar{S}_{ij} = \frac{1}{2} \left( \frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right)$

with Smagorinsky coefficient

$$C = \frac{1}{2} (L_{ij}M_{ij}/M_{ij}^2)$$

using the resolved turbulent stress

$$L_{ij} = -\widehat{u_i u_j} + \hat{u}_i \hat{u}_j$$

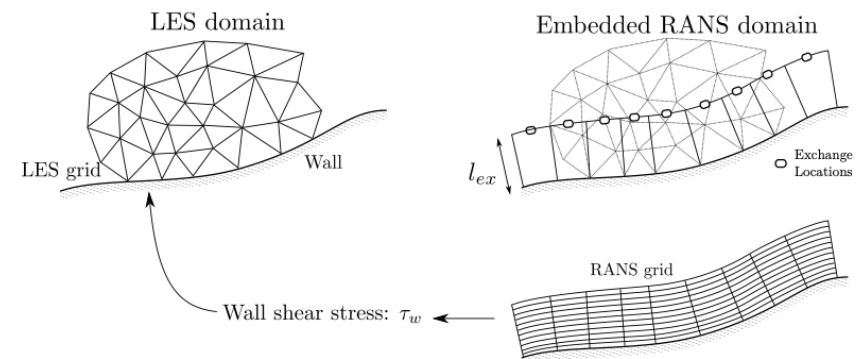
$$\text{and } M_{ij} = \widehat{\Delta^2|\hat{S}|} \hat{S}_{ij} - \Delta^2|\bar{S}|\bar{S}_{ij}$$

- Equilibrium wall model**

*Kawai & Larsson, Phys. Fluids 2012*

Solution of ODE near wall:  $\frac{d}{dn} \left[ (\mu + \mu_R) \frac{dU}{dn} \right] = 0$

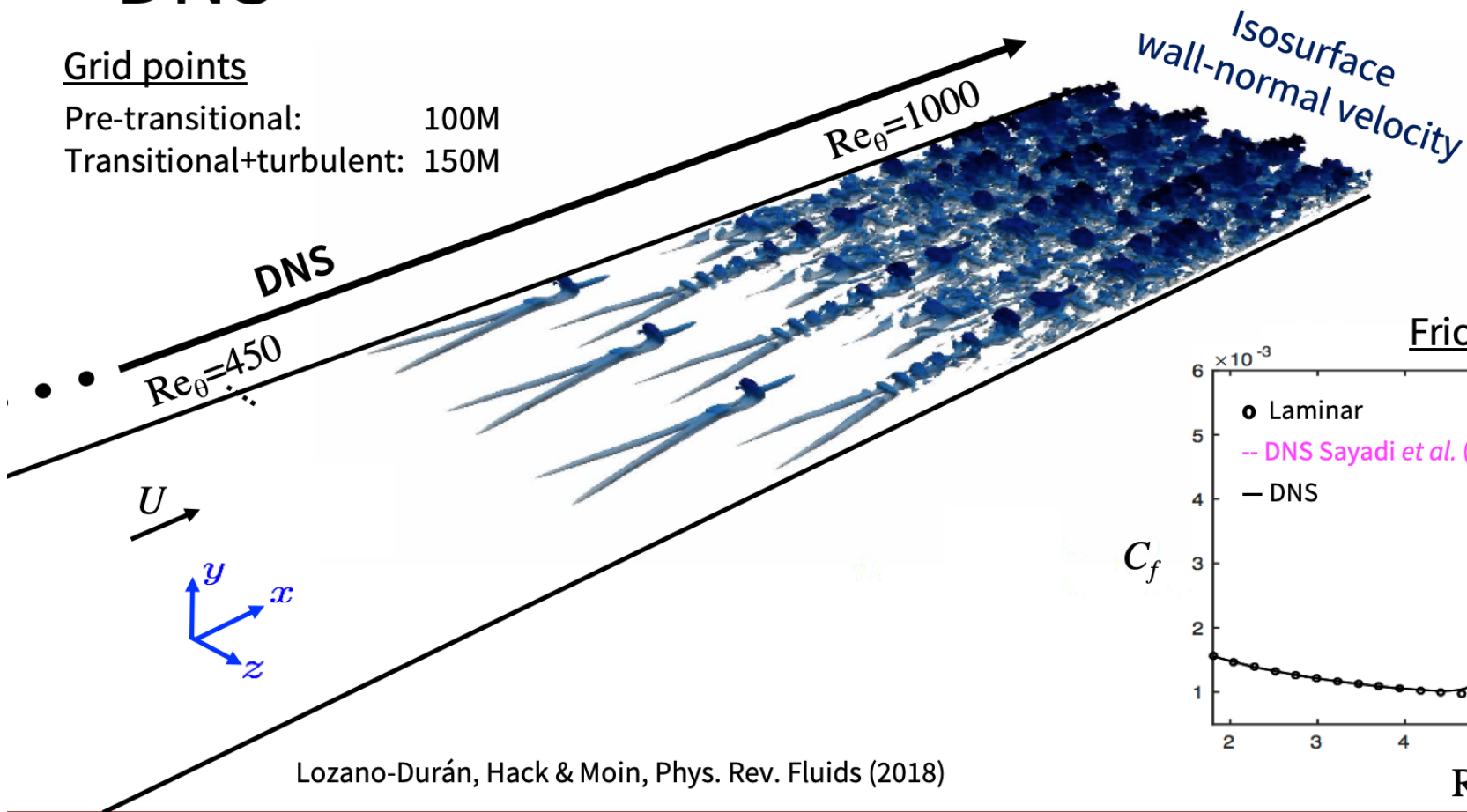
with eddy viscosity  $\mu_R$  taken from mixing-length hypothesis



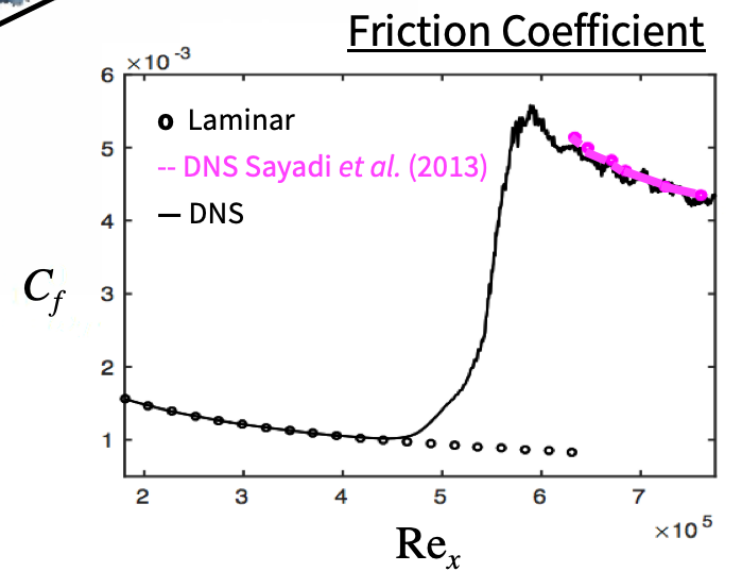
# DNS

## Grid points

Pre-transitional: 100M  
Transitional+turbulent: 150M



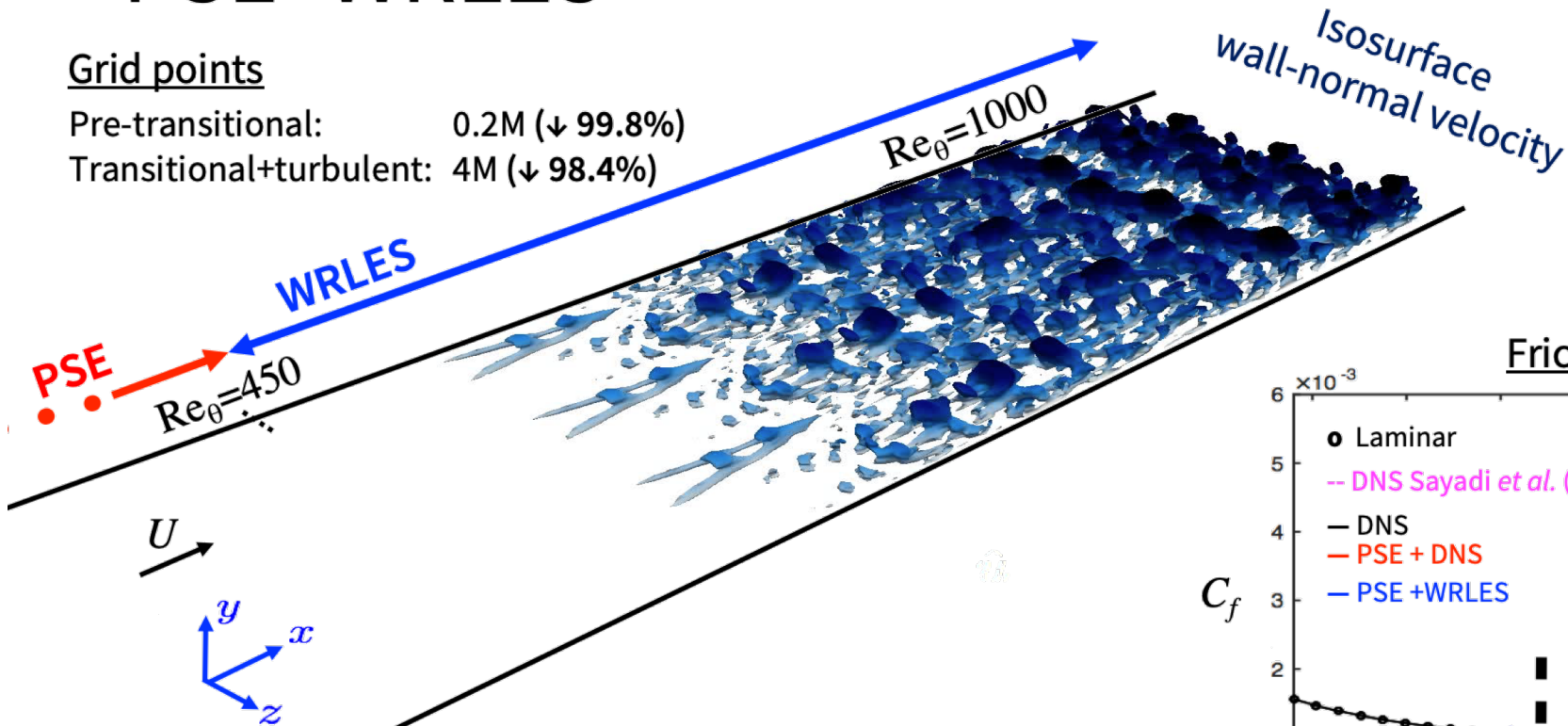
Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)



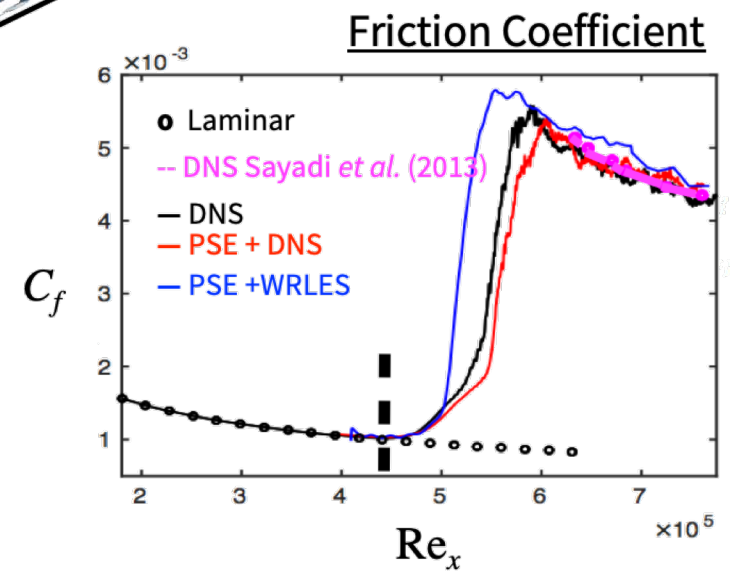
# PSE+WRLES

## Grid points

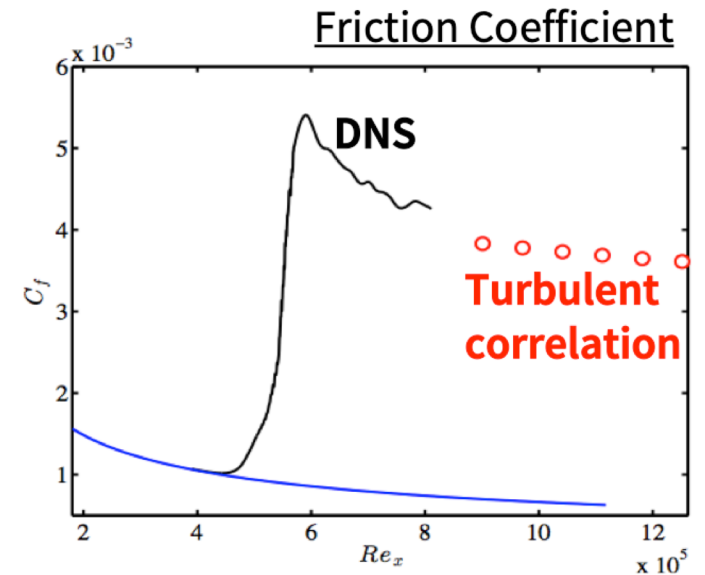
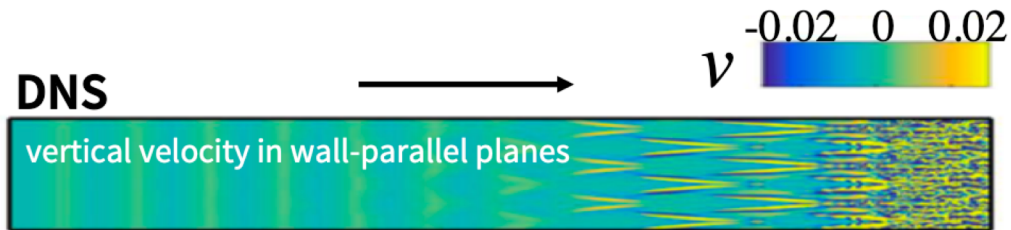
Pre-transitional: 0.2M ( $\downarrow$  99.8%)  
 Transitional+turbulent: 4M ( $\downarrow$  98.4%)



Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)

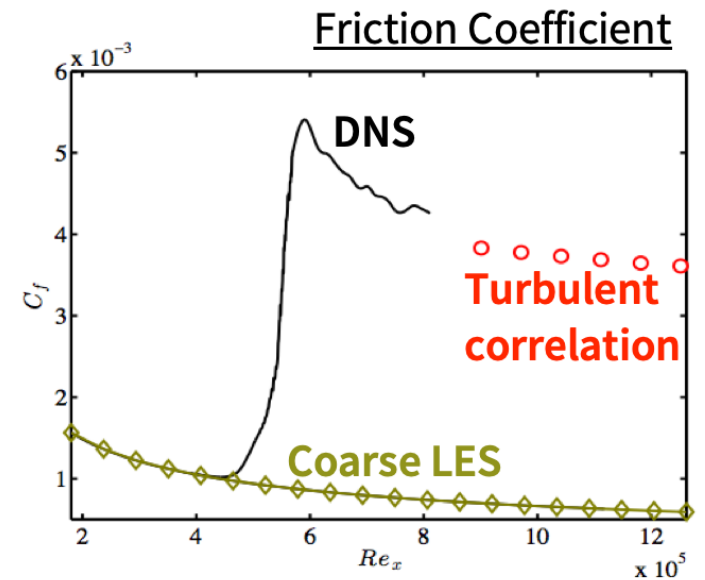
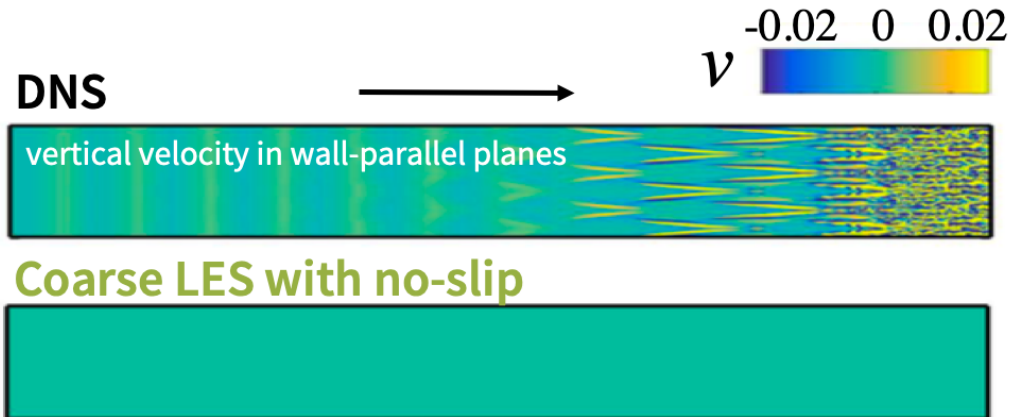


# PSE+WMLES



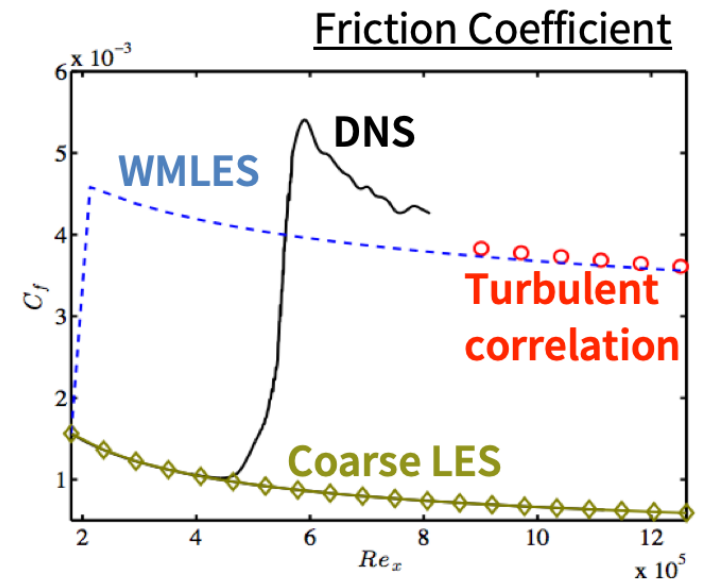
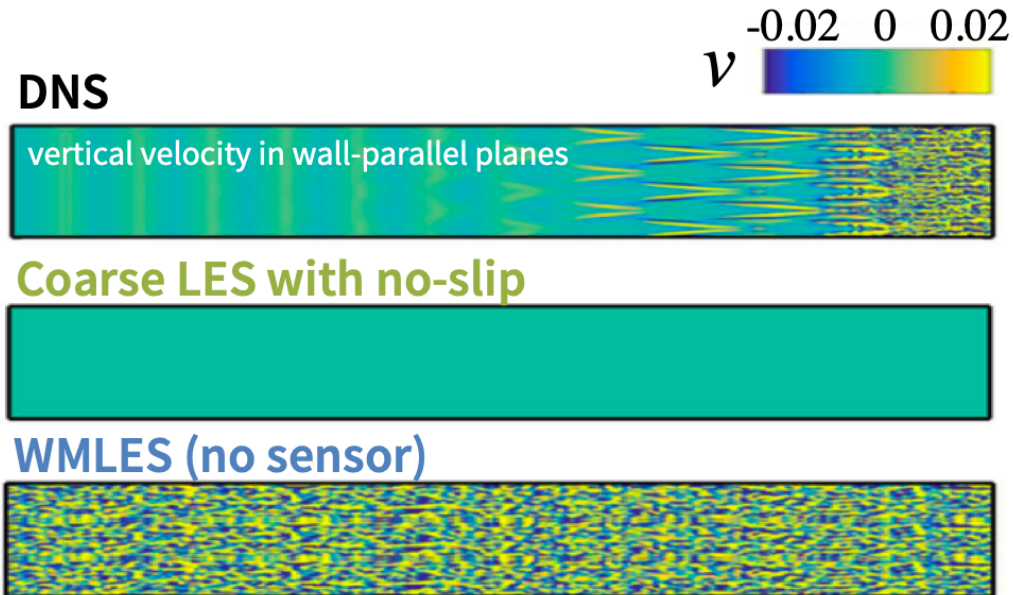
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# PSE+WMLLES



Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)

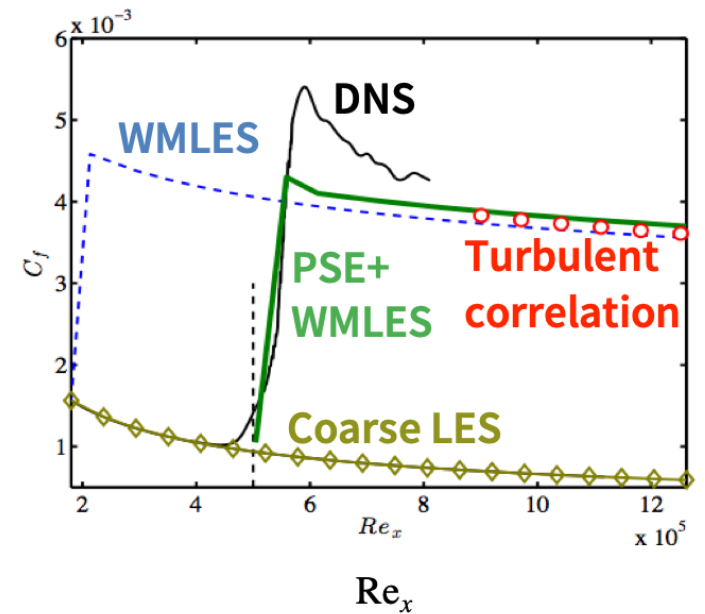
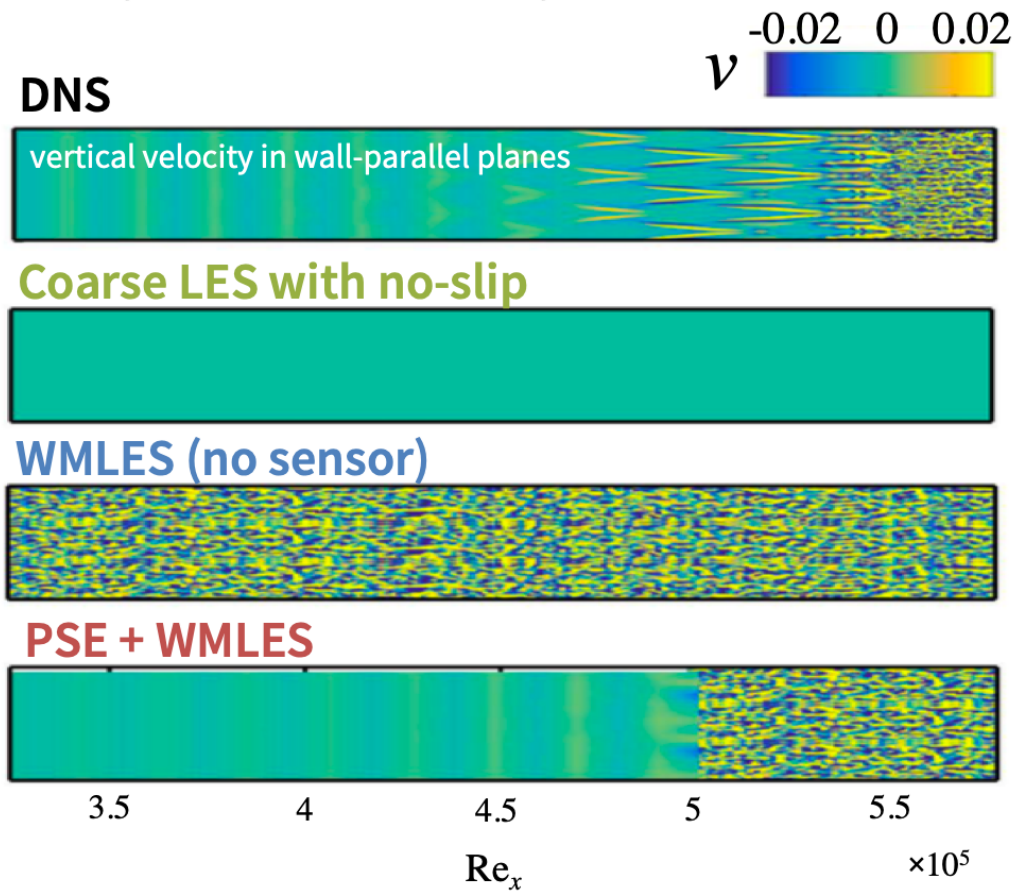
# PSE+WMLES



Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)



# PSE+WMLES

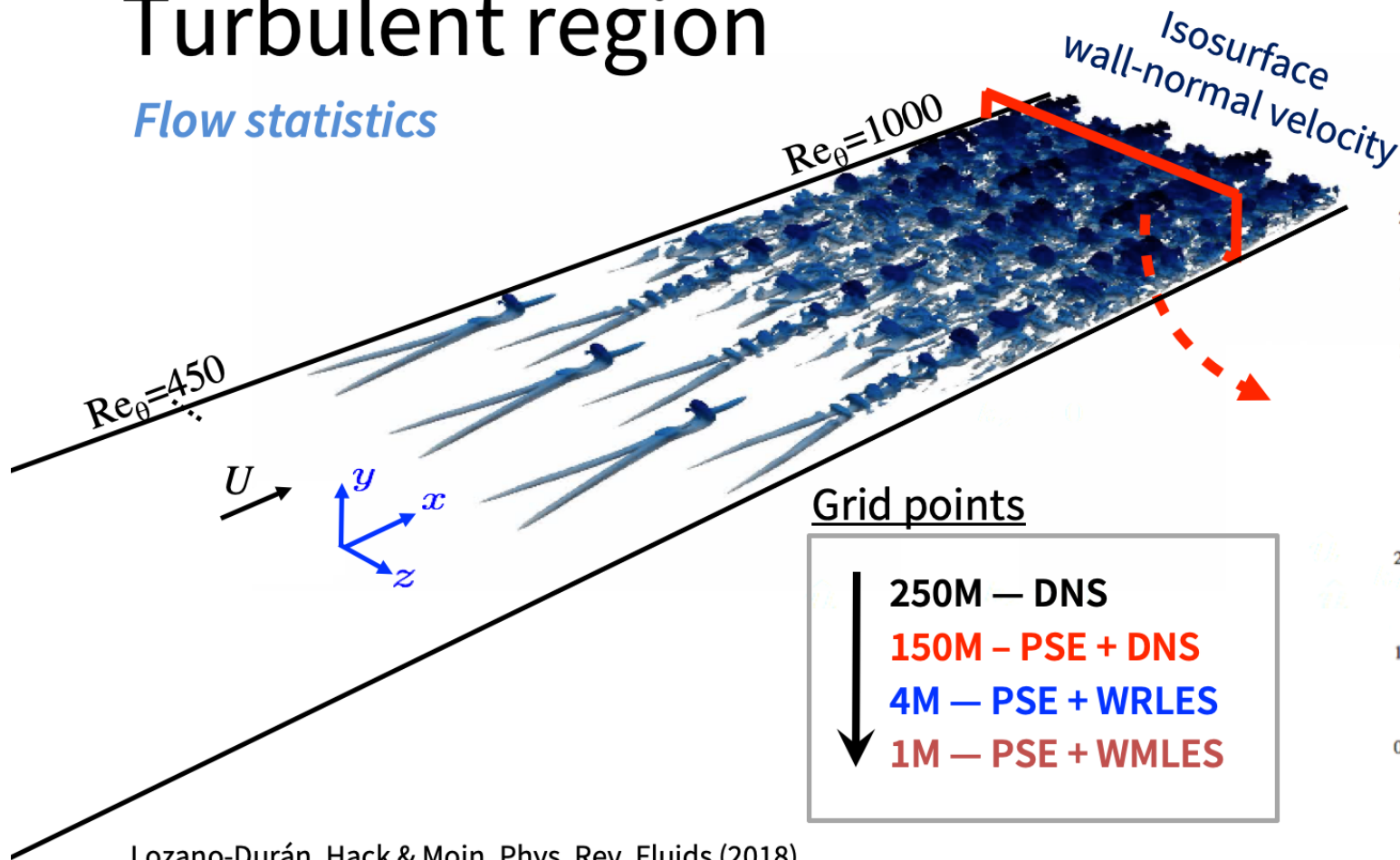


Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)

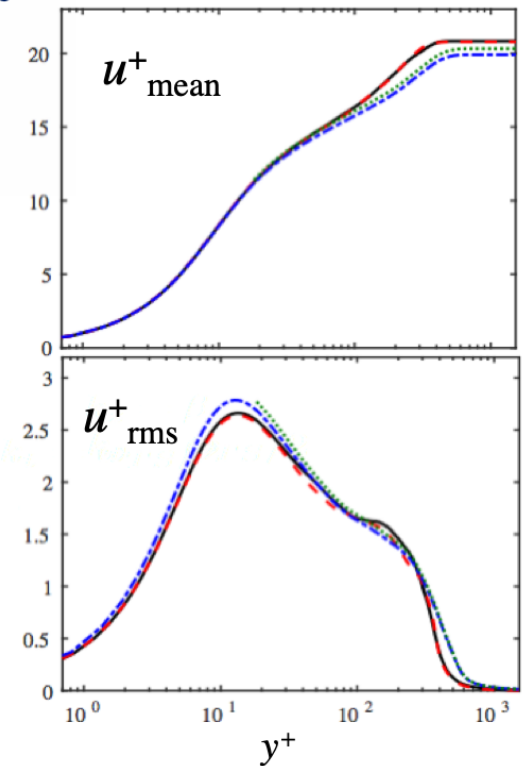


# Turbulent region

*Flow statistics*



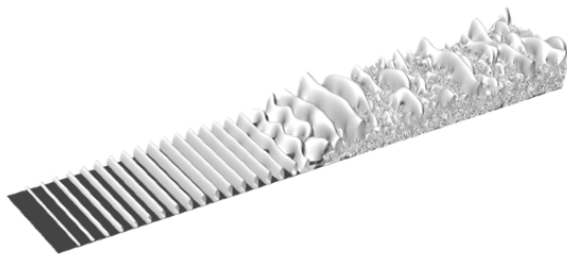
Lozano-Durán, Hack & Moin, Phys. Rev. Fluids (2018)



# Transition scenarios

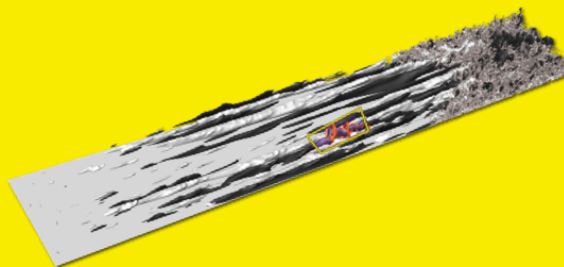
## NATURAL

- Low levels of external disturbances
- Exponential amplification of primary disturbances (TS waves)
- Classical configurations: H/K-type (Herbert 1988, Kachanov 1984)



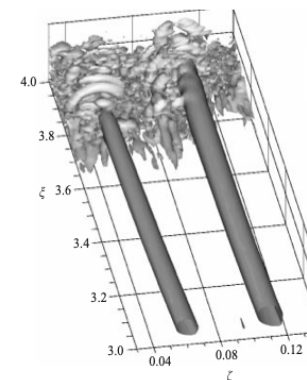
## BYPASS

- Moderate levels of external disturbances
- Algebraic amplification of primary disturbances (streaks)
- Exponential secondary instability



## CROSSFLOW

- Inflectional (exponential) primary disturbance
- Rapid breakdown to turbulence



# Bypass transition

- Faster path to turbulence than transition via Tollmien-Schlichting waves
- Observed in boundary layers exposed to free-stream turbulence (turbo machinery)
- Mediated by the formation of highly energetic streaks inside the boundary layer
- Capturing the mean flow distortion is essential to predict bypass transition

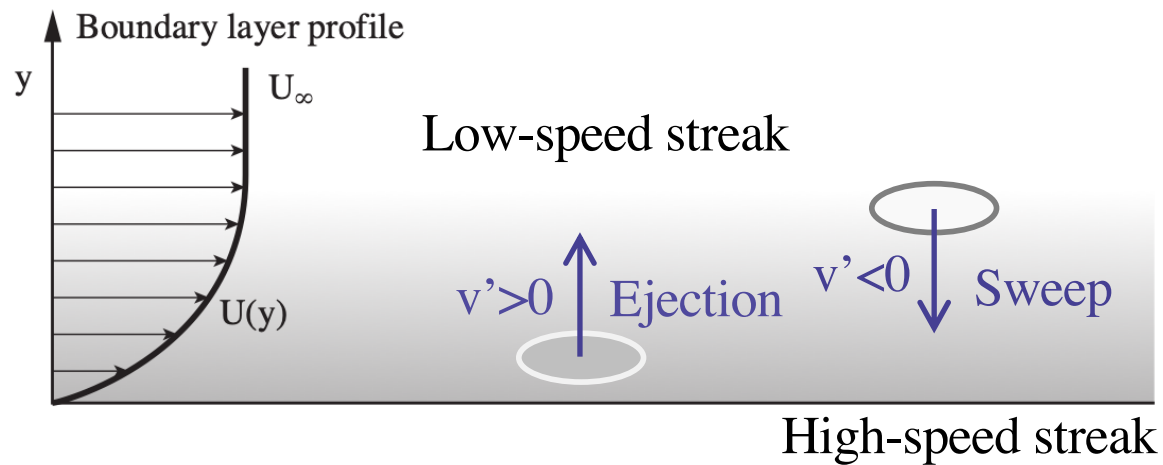


Hack & Zaki, J. Fluid Mech. (2016)

# Streak formation via lift-up

Streaks are the outcome of the displacement of the mean momentum of the boundary layer by wall-normal perturbations (*Landahl 1975*)

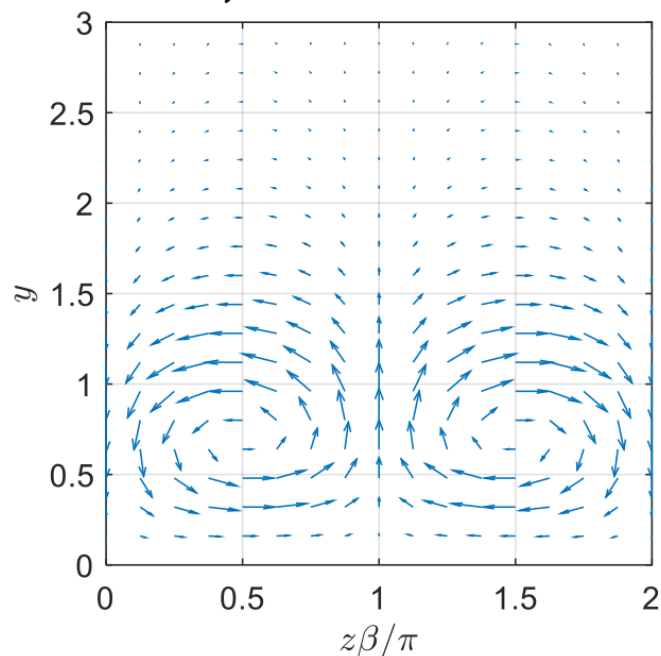
- Ejections lead to low-speed streaks near the edge of the boundary layer
- Sweeps produce high-speed streaks near the wall



# Model problem: periodic streaks

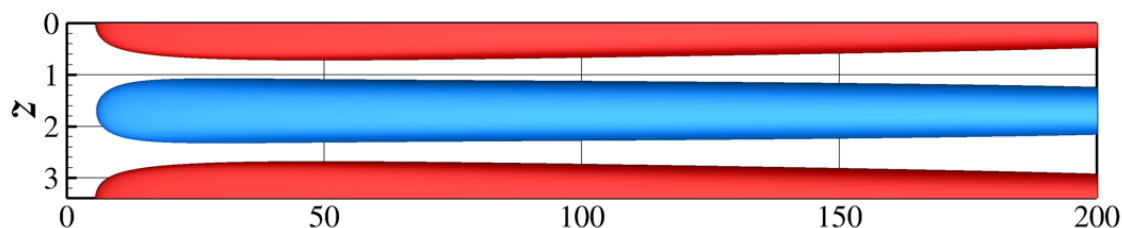
Upstream perturbation:  
counter-rotating vortices

Vector  $v', w'$  — cross-section



Flow response: streaks

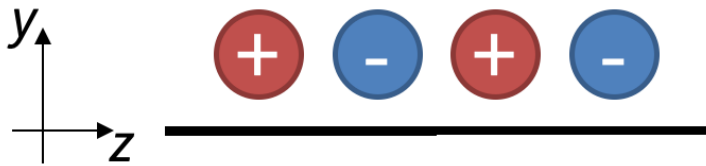
Isosurfaces  $u'$  — top view



→ Transient growth  $x$  generates streaks

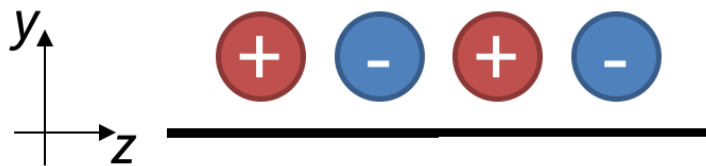
# Mean-flow distortion

Low-amplitude (linear) streaks:

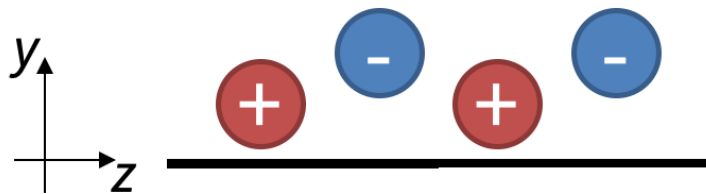


# Mean-flow distortion

Low-amplitude (linear) streaks:

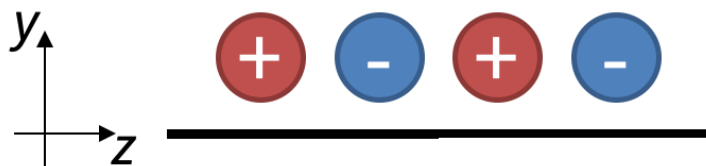


High-amplitude (nonlinear) streaks:

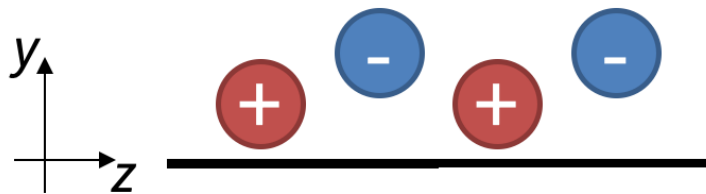


# Mean-flow distortion

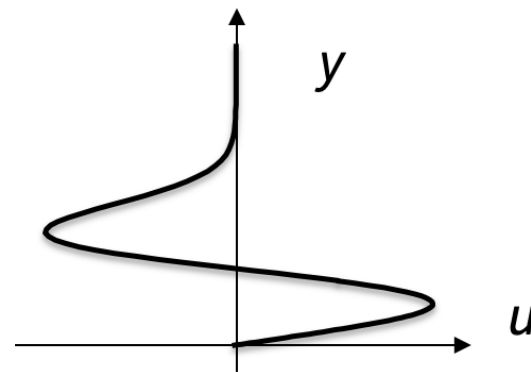
Low-amplitude (linear) streaks:



High-amplitude (nonlinear) streaks:



Mean flow distortion



- High-amplitude streaks modify the mean shear of the boundary layer
- Critically affects the amplification of secondary instabilities

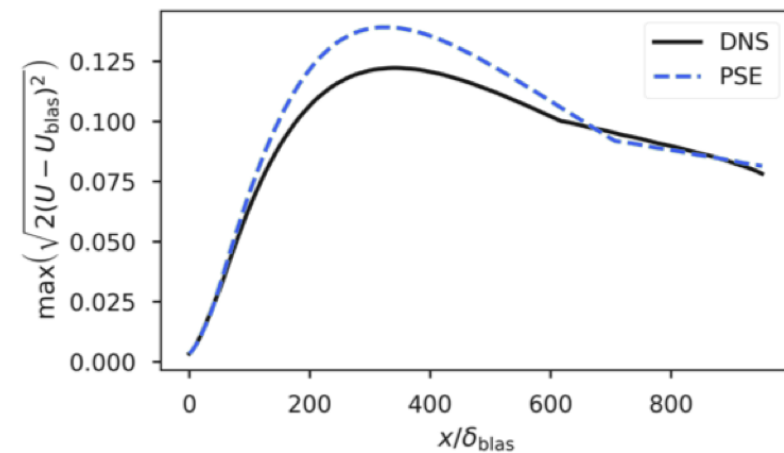
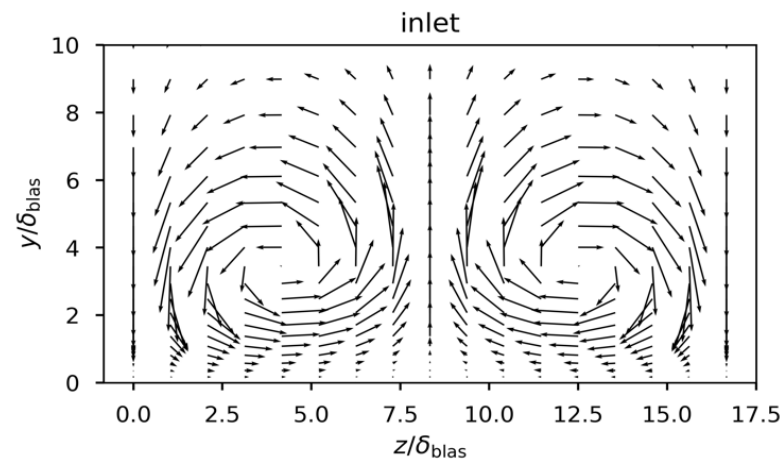


# Mean-flow distortion with PSE

In classical PSE, Mean Flow Distortion (MFD) is handled as a ( $\beta=0, \omega=0$ ) instability mode and added to the Blasius solution

$$Re_{\delta_{blas}} = 162$$

$$\max(\|u\|) = 0.0373$$



→ PSE computation of mean-flow distortion fails for high amplitudes

# Spatial Perturbation Equations (SPE)

- New framework for computing the spatial evolution of nonlinear perturbations
- In the SPE, the base flow is computed by marching the boundary layer equations

Classic boundary layer equations

$$\begin{aligned}\frac{\partial \bar{u}}{\partial x} + \frac{\partial \bar{v}}{\partial y} &= 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial x} + \bar{v} \frac{\partial \bar{u}}{\partial y} + \frac{1}{\rho} \frac{\partial \bar{P}}{\partial x} - \nu \left( \frac{\partial^2 \bar{u}}{\partial y^2} \right) &= 0 \\ \frac{1}{\rho} \frac{\partial \bar{P}}{\partial y} &= 0\end{aligned}$$

# Spatial Perturbation Equations (SPE)

- New framework for computing the spatial evolution of nonlinear perturbations
- In the SPE, the base flow is computed by marching the boundary layer equations
- Addition of forcing terms (averaged nonlinear terms) introduces MFD into the base flow

Classic boundary layer equations

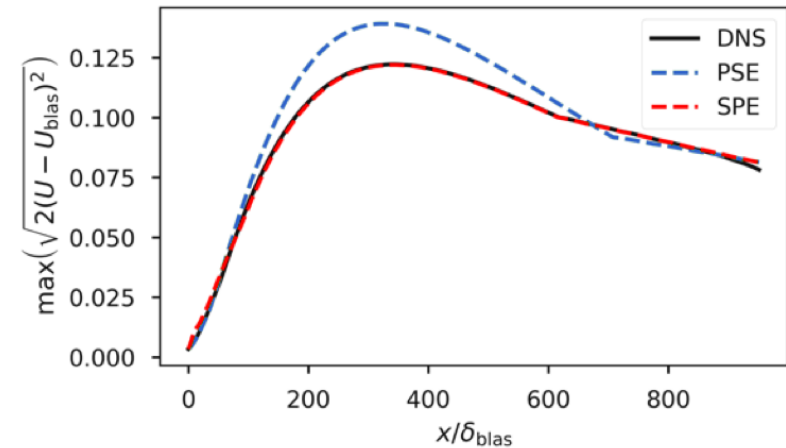
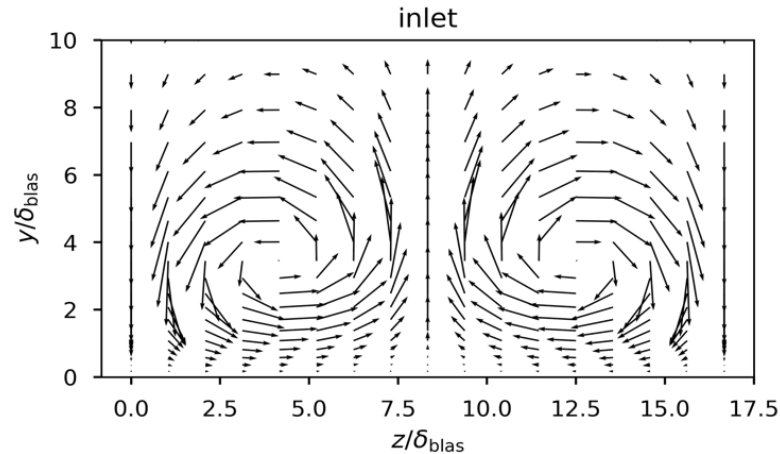
MFD forcing terms

$$\begin{aligned}\frac{\partial \bar{u}}{\partial x} + \frac{\partial \bar{v}}{\partial y} &= 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial x} + \bar{v} \frac{\partial \bar{u}}{\partial y} + \frac{1}{\rho} \frac{\partial \bar{P}}{\partial x} - \nu \left( \frac{\partial^2 \bar{u}}{\partial y^2} \right) &= - \left\langle u'_j \frac{\partial u'}{\partial x_j} \right\rangle \\ \frac{1}{\rho} \frac{\partial \bar{P}}{\partial y} &= - \left\langle u'_j \frac{\partial v'}{\partial x_j} \right\rangle\end{aligned}$$

→ Base flow with MFD obtained from streamwise marching procedure

# SPE mean flow distortion

$$Re_{\delta_{blas}} = 162 \quad \alpha(\|u\|) = 0.0373$$



- SPE captures mean-flow distortion accurately
- Prerequisite for computing bypass transition

# Conclusions

- Parabolized stability equations (PSE) provide an accurate representation of the pre-transitional region including
  - Accurate identification of onset of transition
  - Capturing of growth of individual harmonics
  - Substantial computational savings: from 100M to 0.2M points in pre-transitional regime
  - Combination with WMLES reduces computational cost by factor of 250 compared to DNS
- Computation of bypass transition and accurate capturing of mean-flow distortion poses challenges
- Novel SPE framework computes mean-flow distortion as part of the base flow

**CENTER FOR TURBULENCE RESEARCH**

